



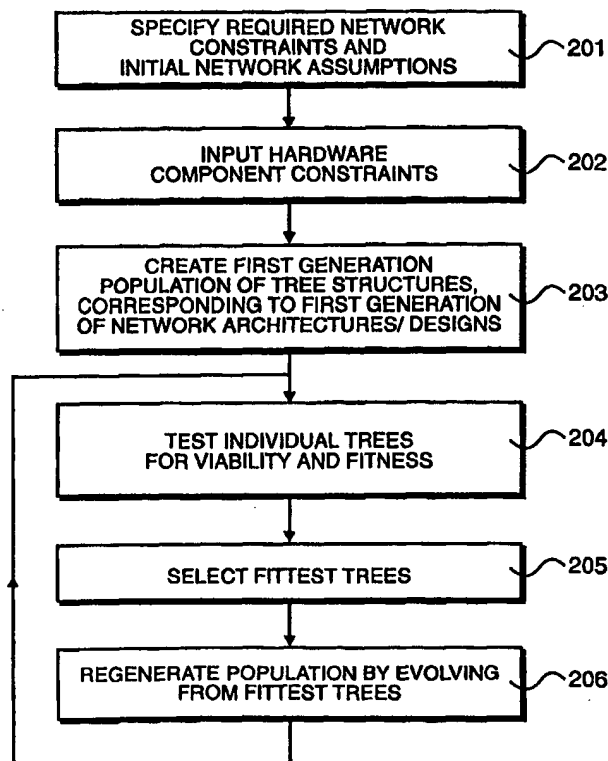
INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification ⁶ : H04Q 3/00		(11) International Publication Number: WO 98/03023
A1		(43) International Publication Date: 22 January 1998 (22.01.98)
(21) International Application Number: PCT/GB97/01842 (22) International Filing Date: 9 July 1997 (09.07.97) (30) Priority Data: 9614927.3 16 July 1996 (16.07.96) GB (71) Applicant (for all designated States except US): BRITISH TELECOMMUNICATIONS PUBLIC LIMITED COMPANY [GB/GB]; 81 Newgate Street, London EC1A 7AJ (GB). (72) Inventor; and (75) Inventor/Applicant (for US only): ROBINSON, Gerald, Anthony [GB/GB]; Brook Cottage, Icknield Street, Beoley Redditch, Worcestershire B98 9AL (GB). (74) Agent: ATKINSON, Ralph; Atkinson & Co., The Technology Park, 60 Shirland Lane, Sheffield S9 3SP (GB).		(81) Designated States: AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, CA, CH, CN, CU, CZ, DE, DK, EE, ES, FI, GB, GE, GH, HU, IL, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MD, MG, MK, MN, MW, MX, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, SL, TJ, TM, TR, TT, UA, UG, US, UZ, VN, YU, ZW, ARIPO patent (GH, KE, LS, MW, SD, SZ, UG, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, CH, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, ML, MR, NE, SN, TD, TG). Published With international search report.

(54) Title: PROCESSING DATA SIGNALS

(57) Abstract

A network's components are represented in the form of data signals arranged into a hierarchical tree structure. A population comprising a large number of randomly created tree structures, each relating to an individual network, is generated. The tree structures undergo a process of evolution through successive generations, by selectively breeding the most successful tree structures. Through the process of breeding, one or a plurality of optimal tree structures emerges. A network is constructed in accordance with the data signals represented by the optimal tree structure. The network may be any network comprising a set of nodes and links, e.g. a gas pipeline network, an electricity supply network, a water pipeline network or the like, but the disclosure is particularly relevant to a telecommunications network or a computer network.



FOR THE PURPOSES OF INFORMATION ONLY

Codes used to identify States party to the PCT on the front pages of pamphlets publishing international applications under the PCT.

AL	Albania	ES	Spain	LS	Lesotho	SI	Slovenia
AM	Armenia	FI	Finland	LT	Lithuania	SK	Slovakia
AT	Austria	FR	France	LU	Luxembourg	SN	Senegal
AU	Australia	GA	Gabon	LV	Latvia	SZ	Swaziland
AZ	Azerbaijan	GB	United Kingdom	MC	Monaco	TD	Chad
BA	Bosnia and Herzegovina	GE	Georgia	MD	Republic of Moldova	TG	Togo
BB	Barbados	GH	Ghana	MG	Madagascar	TJ	Tajikistan
BE	Belgium	GN	Guinea	MK	The former Yugoslav Republic of Macedonia	TM	Turkmenistan
BF	Burkina Faso	GR	Greece			TR	Turkey
BG	Bulgaria	HU	Hungary	ML	Mali	TT	Trinidad and Tobago
BJ	Benin	IE	Ireland	MN	Mongolia	UA	Ukraine
BR	Brazil	IL	Israel	MR	Mauritania	UG	Uganda
BY	Belarus	IS	Iceland	MW	Malawi	US	United States of America
CA	Canada	IT	Italy	MX	Mexico	UZ	Uzbekistan
CF	Central African Republic	JP	Japan	NE	Niger	VN	Viet Nam
CG	Congo	KE	Kenya	NL	Netherlands	YU	Yugoslavia
CH	Switzerland	KG	Kyrgyzstan	NO	Norway	ZW	Zimbabwe
CI	Côte d'Ivoire	KP	Democratic People's Republic of Korea	NZ	New Zealand		
CM	Cameroon	KR	Republic of Korea	PL	Poland		
CN	China			PT	Portugal		
CU	Cuba	KZ	Kazakstan	RO	Romania		
CZ	Czech Republic	LC	Saint Lucia	RU	Russian Federation		
DE	Germany	LI	Liechtenstein	SD	Sudan		
DK	Denmark	LK	Sri Lanka	SE	Sweden		
EE	Estonia	LR	Liberia	SG	Singapore		

PROCESSING DATA SIGNALS

The present invention relates to a network of nodes and links designed and/or optimized using a genetic process, and particularly, although
5 not exclusively to a communications network.

Introduction

There are numerous examples of utility service networks which comprise a plurality of nodes interconnected by a plurality of links. Services
10 are transferred between node equipment at the nodes along link equipment. Examples of such networks include electricity supply networks, in which the links comprise high voltage power cables and the nodes comprise power stations, generators, substations and the like; water supply networks in which the node equipment comprises reservoirs, valves, water towers, and
15 customer sites, and the links comprise supply pipelines; gas supply networks where the node equipment comprises sea platforms, storage tanks, customer sites, distribution centres and valves, and the links comprise gas pipelines; Intercity road networks in which the nodes comprise towns or cities and the links comprise roads, and similarly railway networks and airline networks, and
20 more particularly communications networks such as a computer network in which the nodes may comprise computer equipment and the links may comprise communication links, or telephony service communications networks, in which the nodes may comprise exchange equipment, and the links may comprise terrestrial, undersea, airborne or satellite communications
25 channels.

Taking the example of the telephone service network, a conventional telecommunications network comprises a plurality of exchanges for connecting and directing communications channels between customer sites, and a plurality of communications links connecting the exchanges and the
30 customer sites. A customer site may comprise a single piece of equipment, for example a single telephone handset, or may comprise a switchboard facility at a customer's premises, enabling incoming calls to be directed to a plurality of individual telephone handsets.

Where it is required to connect a new customer site to an existing communications network, or where it is required to set up a communications network in a locality from scratch (a "green field" network) the design of the new network, or the design of the modification to the network, is conventionally carried out by a human designer or a team of designers. Network design is a skilled activity that relies on human expertise. There are sections of networks which can be automatically designed, once the necessary design parameters or specifications for the network have been established. Particular sections of a network may be designed by existing algorithms and design techniques implemented by computer. Nevertheless, in general, human network designers tend to use such algorithms and techniques as tools in designing a network, and unless the human network designers can be convinced that the tools produce an optimum solution to the problem of network design, the human designers will generally rely upon their own experience and intuition in designing a network, rather than relying upon the algorithms to produce a design for a complete network.

The number and variety of parameters that the human network designer must take account of in designing a network is large. Some of the parameters familiar to human designers of telecommunications networks include selecting the type of switching network, for example packet switched network or circuit switched network (PSN or CSN), layout of network topology, availability, growth, survivability, reliability, delay, performance, cost, call blocking, grade of service, quality of service, hops, capacity, bandwidth, and fixed alternative or dynamic alternative routing. Further, synchronous and asynchronous networks require different approaches to design optimization.

Summary of the Invention

According to a first aspect of the present invention, there is provided a method of processing data signals representing a plurality of networks, each network comprising a plurality of node equipment at nodes of the network, and connecting the node equipment a plurality of links each comprising link equipment, said method comprising steps of: generating a population of

individual hierarchical signals, each describing a respective network; testing each hierarchical signal to check that it represents a viable network; testing each hierarchical signal which represents a viable network against one or more predetermined test parameters; selecting a set of said hierarchical signals depending upon a result of said step (c); evolving said set of selected hierarchical signals to produce a next generation population of hierarchical signals.

Brief Description of the Drawings

10 The invention will now be described by way of example only with reference to the following drawings, of which:

Figure 1 shows a functional layout of hardware for implementing a preferred method according to the present invention;

15 Figure 2 shows a general overview of a preferred method according to the present invention;

Figures 3 and 4 show schematically further detail of a preferred method according to the present invention;

Figure 5 shows a configuration of a link signal comprising the preferred method;

20 Figure 6 shows another configuration of a link signal;

Figure 7 shows yet another configuration of a link signal;

Figure 8 shows a configuration of a graft signal according to the preferred method;

Figure 9 shows another configuration of a graft signal;

25 Figure 10 shows schematically an operation of the link signal;

Figure 11 shows schematically an operation of the graft signal;

Figure 12 shows a tree structure according to one embodiment of the present invention;

30 Figures 13 - 16 illustrate visual displays of a telecommunications network in accordance with the tree structure of Figure 12, as displayed on a display device;

Figure 17 shows a visual display of the network described by the tree structure of Figure 12, as displayed on a display device;

Figure 18 illustrates a network design problem for linking a plurality of customer sites;

Figure 19 shows a tree structure created to provide a possible solution to the network design problem of Figure 18;

5 Figure 20 illustrates a visual display on a display device of a network map representing a possible solution to the network design problem of Figure 18 as described by the tree of Figure 19;

Figure 21 shows another tree structure created to provide another possible solution to the network design problem of Figure 18;

10 Figure 22 shows a visual display on a display device of another network map representing a possible solution to the network design problem of Figure 18 as described by the tree of Figure 21;

Figure 23 shows evolution of the first and second tree structures of Figures 19 and 21, to create a further generation of offspring tree structures;

15 Figure 24 shows visual displays as presented on a display device of parent and offspring network maps described by the parent and offspring tree structures of Figure 23;

Figure 25 illustrates a visual display as presented on a display device of a randomly generated network map as a first generation attempt solution
20 to a second network design problem;

Figure 26 illustrates a visual display on a display device of an optimized network map as an optimized solution to the second network design problem;

25 Figure 27 shows a visual display on a display device of a set of initial network constraints and initial network assumptions for a third network design problem;

Figure 28 shows a visual display on a display device of an initial generation network map representation, described by an initial generation randomly generated tree structure, including the constraints and assumptions
30 of the network described by Figure 26; and

Figure 29 shows a visual display on a display device of an optimized solution network map to the third network design problem having initial network assumptions, described by the display of Figure 26;

Detailed Description of the Preferred Embodiments

The invention will now be described by way of example only, with reference to the drawings identified above.

5 A general overview for a network design apparatus is shown in Figure 1, which utilizes a machine implemented genetic process for optimization of the network comprising nodes and links. A physical network is represented as a two dimensional network map comprising a plurality of nodes and a plurality of links. The network design apparatus may be used for arranging
10 data signals defining a design of any network comprising node equipment and links equipment, eg a utilities services network such as a gas pipeline network, a road network, an airline network, an electricity supply network, a water distribution network or a communications network, for example a computer network or a telecommunications network. Hereinafter, by way of
15 example the network design apparatus and its method of operation by arrangement of data signals will be described using the example of a communications network, and more particularly, a telecommunications network.

 The network map comprises a comprehensive set of instructions for
20 building a physical network. The nodes of the map represent pieces of physical node equipment and their locations. The links of the map represent physical telecommunications links, eg. in the case of a telecommunications network, fibre optic cables, microwave paths. The network map contains data representing the physical locations of nodes and links relative to one another,
25 or relative to a predetermined geography, along with other characteristics relevant to the network, for example in the case where the network design apparatus is used to design a telecommunications network, the network map contains data representing routing tables, link and exchange capacities, service functions, and data describing costs or other performance criteria of
30 hardware components. The network map may be stored in electronic form as a network signal in an electronic processor or memory.

 The apparatus in Figure 1 comprises a tree generator 140 which receives hardware signals representing data describing physical exchange

apparatus, link apparatus, customer site equipment and other equipment of a telecommunications network, network assumption signals representing data concerning any initial assumptions about the type of network likely to be designed and network constraint signals representing any constraints on the network required. The tree generator 140 comprises a portion of electronic memory and an electronic processor. The hardware signals, network assumption signals and network constraint signals may be received by transfer from a signal carrier such as a floppy disk 141 to an electronic memory, assigned to the tree generator 140. The processor operates in accordance with a set of predetermined assembly signals, which may be input from a signal carrier for example a floppy disk 143, in order to assemble the hardware signals into a hierarchical tree structure in which the hardware signals are encapsulated by node signals and connection signals, the connection signals connecting together the node signals.

The node signals and connection signals may be input to the tree generator via a signal carrying medium such as a floppy disk 144. Assembled tree signals are transmitted to a tree signal to network signal converter 145 which implements the instructions contained in the connection signals and node signals in order to create a set of network signals describing a physical telecommunications network. Each tree signal describing a respective hierarchical structure of hardware signals, node signals and connecting signals is converted into a respective network signal representing a single physical telecommunications network, by the tree to network converter 145. The network signal representing the physical telecommunications network comprises the network map in signal form. The tree generator may generate a large initial population of tree signals, for example 500, which are stored in the tree memory 142 and each tree signal is converted by the tree signal to network signal converter 145 into a respective network signal, resulting in a large population, for example 500, of network signals each defining a respective network map.

The tree to network converter 145 preferably comprises an electronic processor configured to implement the instructions contained in the node signals and the connection signals. From each network signal, can be

derived a resulting visual network display representing the network map for display on a display device 146. The network signals may undergo further electronic processing in order to configure them to a format suitable for display on the visual display device 146. Alternatively, the network signals
5 can be configured to produce hard copy representations of the network map represented by the network signals, to be printed out on a printer device 147. The network signals can be downloaded onto a signal carrier, eg a floppy disk, by a suitable device such as a floppy disk drive 148. Network signals are transmitted from the tree signal to network signal converter 145 to a
10 viability evaluator 149. The viability evaluator tests the network described by the network signals against predetermined viability criteria signals, which may be downloaded from a signal carrier, eg a floppy disk 150 into the viability evaluator.

Network signals which are within viability criteria defined by the
15 viability criteria signals are transmitted to a fitness evaluator 151. The fitness evaluator evaluates the networks described by the network signals against fitness criteria conditions described by fitness criteria signals which may be downloaded from a signal carrier such as a floppy disk 152. The viability evaluator and the fitness evaluator may each comprise an electronic
20 processor. The fitness evaluator outputs a fitness signal for each network signal operated on by the fitness evaluator. The fitness signal is transmitted to a tree selector 153, which preferably comprises an electronic processor. The tree selector 153 compares the fitness signals produced by the fitness evaluator with a set a predetermined fitness limit signals which may be
25 downloaded from a signal carrier such as a floppy disk 154, and generates a selection signal for each network signal which has resulted in a viability signal and a fitness signal which fall within respective limits defined by the corresponding viability criteria signals and fitness limit signals.

The selection signals are input to a genetic evolution engine 155
30 which evolves selected tree signals transmitted from the tree memory 142, by combining and reproducing tree signals with each other, to produce modified tree signals which are then retransmitted to the tree signal store 142. The process of evolution of the tree signals is controlled by a set of instructions

contained in evolution signals which may be downloaded to the genetic evolution engine via a signal carrier, eg a floppy disk 156. Preferably the genetic evolution engine 155 comprises an electronic processor with an associated portion of memory, eg RAM. Modified tree signals in the tree signal memory 142 are then sent to the tree signal to network signal converter 145, and the process as described above is repeated on the modified tree signals. This results in a new set of tree signals which are operated on by the genetic evolution engine 155. Each time a selected set of tree signals are operated on by the genetic evolution engine 155, a new generation of modified tree signals are overwritten into the tree signal memory 142. A number of generations may be selected, and for any generation, displays representing physical networks represented by the network signals corresponding to that generation of tree signals may be obtained on the visual display device 146, or the printer 147.

In a preferred embodiment, the tree generator, viability evaluator, fitness evaluator, tree selector and genetic evolution engine are implemented by configuring an electronic computer, for example by configuring a UNIX platform in the programming language C. Tree signals and/or network signals may be unloaded from the tree to network converter 145 by means of a hard disk drive 152.

Referring to Figure 2 herein there is described a general overview of a process implemented by the apparatus of Figure 1, for obtaining tree signals. Each tree signal is convertible into a set of network signals representing a design (the network map) for a respective telecommunications network. The result of the process is a set of signals representing designs for a telecommunications network. The signals may be used to drive a display device or printer, in order to produce a hard copy network map for a telecommunications network. A physical telecommunications network may be built in accordance with the information contained in the network maps. Since the construction and operation of the telecommunications network is dictated by its overall design, as embodied by the tree signals, the process for designing the network is implicitly part of the physical telecommunications network itself. The tree signals resulting from the process described herein,

dictate the operation and functioning of a physical telecommunications network.

At step 201 the commencement of the process comprises specifying a set of required constraints of the network, and making any initial assumptions
5 about the type of network required eg the number and locations of exchanges. This step is implemented by creating data signals representing the network constraints and network assumptions. Step 201 may be thought of as defining a problem to which an optimized solution is to be found.

At step 202, hardware signals representing the physical constraints of
10 individual hardware components which are available for inclusion in the physical network is collected. Such data signals may be available as data signals stored in a database on a computer, or may be input from a signal carrier, eg floppy disk 141.

At step 203, an initial population of hierarchical two dimensional tree
15 structure signals are generated. Each tree structure signal represents data which specifies a particular network design as a possible solution to the problem of obtaining an optimum network design within the specified constraints. Typically a population of individual tree signals of size sufficient to give a wide variety of solutions is generated, for example 500 tree signals,
20 although the exact number could vary within wide limits of this figure. The tree signals are generated by a random or part random process, in accordance with a set of assembly instructions which assemble node signals, connecting signals and constraint signals into a two dimensional tree signal.

At step 204, each individual tree structure is converted to a respective
25 network signal, which is tested for viability and for fitness as a network design. Each network signal is tested in respect of the viability of the physical telecommunications network which it represents. Since the trees are initially randomly generated, not all trees will result in network signals which describe designs which are physically viable.

30 Fitness testing comprises testing a network design represented as a network signal resulting from an individual tree against a defined fitness criteria, for example performance, reliability, resilience or cost. Each individual tree signal is accorded a measure of its fitness.

A predetermined percentage of the tree signals of the initial population are selected at step 205 to form the base from which a next generation population of tree signals will evolve. Since the majority of the least fit trees are unlikely to be selected as the basis of the next population, the number of
5 selected tree signals will be lower than the number of the tree signals in the initial population.

At step 206, the population is regenerated by evolving new tree signals from the selected viable tree signals of the initial population. Regeneration of the tree signals may be through the mechanisms of
10 crossover, reproduction in unchanged form, mutation, or permutation.

The number of individual tree signals in the regenerated population will be larger than the number of tree signals selected, due to some tree signals having more than one offspring. The number of tree signals in the regenerated population may be brought up to match the number of tree
15 signals in the original population. The regenerated population then undergoes further viability and fitness testing at step 204 and further selection and regeneration at steps 205 and 206.

The selection of tree signals is made by assigning a probability of selection to each individual tree signal, the probability determined by the
20 fitness accorded to each tree signal as a result of the fitness testing. The fitter tree signals are more likely to be selected than the less fit tree signals. By the process of selection of the tree signals based on their fitness score, it can be expected that the average fitness of each population increases with time. Further, individual viable tree signals having outstanding fitness may appear
25 in some generations, representing an optimal network design.

Steps 204, 205 and 206 are repeated until a predetermined number of generations have evolved, or a predetermined time has elapsed since creation of the initial population, or until further regeneration of the population produces little or no increase in average fitness, or if an individual tree signal
30 or individual set of tree signals evolves having a fitness upon which it is difficult to improve.

Referring to Figure 3 of the accompanying drawings, a specific preferred process, being an example of the general preferred process of

Figure 2 is described. At step 301 required network constraints and initial network assumptions are included as network constraint signals and network assumption signals. The constraint signals may describe required input parameter data signals and output parameter data signals to the network in order to define a specification for a network design.

At step 302 constraints of the network hardware components are specified by hardware signals.

At step 303, an initial population of tree signals is generated, each tree signal representing a respective network architecture or network design (ie a particular network map). Each tree signal is assembled by a processor in accordance with assembly instructions implemented by assembly signals, such that a set of the hardware signals representing hardware components are encapsulated in node signals and connecting signals. The node signals are linked together by the connecting signals into a two or more dimensional hierarchical structured tree signal. Each tree signal represents a set of instructions for operating a processor to produce a set of network signals which describe a physical communications network.

At step 304, the viability of a network design resulting from each tree signal is tested by comparing the network design resulting from the tree structure with a set of viability criteria signals. If the network is within those constraints, then the network is viable. If it is not inside those constraints then the network is not viable.

The fitness of each tree of the population is determined by converting the tree signal into a network signal representing a network design, and then by simulating the behaviour of that design under typical operating conditions, by processing the network signal in accordance with signals representing call traffic flow, call traffic bandwidth, call traffic routing, and other traffic which the network is expected to carry, or by calculating the cost of assembling a network of that design by summing signals representing the cost of individual components represented by the network signal. The behaviour of the design is simulated by processing the network signal along with signals representing input parameter values to produce resultant signals representing respective sets of values for performance, reliability, resilience and cost.

At step 305, successful trees are selected from which to evolve. Tree signals which produce unsatisfactory networks are rejected.

At step 306 (Figure 4), regeneration of the population is made by combining sections of a proportion of the selected trees to produce a next population of trees, and by maintaining a percentage of the successful trees into the next generation.

Further variations and modifications of the processes of Figures 2 and 3 as implemented by the apparatus of Figure 1 will be described below.

10 **Network constraints and initial assumptions about the network**

In order to define a network design problem for which an optimized solution is to be found, there need to be defined certain constraining parameters about the network which must be met for the network to be a viable solution to the problem. For example, if a problem is to design a network connecting four customer locations, then network designs which connect only three of the four locations will not be viable networks. The condition of connecting all four locations is a constraint on the network to be designed. Another example of a constraint may be a cost constraint. If a network has a limited cost budget, then to be viable any network designs must be capable of being implemented for a cost lower than the cost budget. Networks which have a cost higher than the cost budget, will not be viable designs from the point of view of cost. Network constraints are entered into the process by means of entering network constraint signals into an electronic memory.

Examples of network constraints which may be termed as "viability constraints" are as follows:

- all customer sites are connected.
- average cumulative delay time along all possible routes is below a specified limit.
- a maximum number of hops per route is less than a selected number.
- an average value of the link capacity ratio is within selected limits.

- the overall cost of the network is within selected limits.
 - reliability or survivability of the network is within selected limits.
 - all exchanges of the design have the necessary switching and concentration capacity to cope with the traffic on the attached links.
- 5 • any initial assumptions about the network are met, eg all of the external exchanges included in an initial assumption are included in the network.

Viability constraints may be entered into the process in steps A or D as a set of viability constraint signals. In order to provide a population of tree structured signals which represent networks which are likely to fulfil the viability criteria, initial assumptions about the type of network architecture that will form a solution to the problem may be made prior to creating a generation of tree structures. For example, a minimum number of exchanges may be assumed, a minimum capacity exchange may be assumed or a minimum number of links may be assumed. The initial network assumptions and network constraints are input as network assumptions signals and network constraint signals to the tree generator 140. The initial network constraints specified, and the network assumptions made define the environment of the optimization process, and reduce the search space in which the process searches for an optimum network.

Several basic types of network design optimization problems which arise, and which have a bearing on the initial assumptions and network constraints specified can be classified as follows:

25 1. LAL - local access loop design

If a network is to connect up hundreds of telecommunications users' traffic source and sink nodes, then it is usually considered sensible to separately cluster together and interconnect a number of groups of those users into separate local access loops as a first stage of a design process.

30 The separate local access loops themselves can then be connected together via access points at a second stage of the design process.

2. BBN - backbone network design

A backbone network can be designed by considering the "local loop" access points as separate traffic source and sink nodes each representing a group of telecommunications users, and connecting them together with higher capacity components.

3. NED - network expansion design

In the context of providing new telecommunications services to existing telecommunications customers, a network design problem is how to upgrade an existing telecommunications network, rather than to build a new telecommunications network from scratch.

4. SO - survivability optimization

Of particular relevance to a backbone network design, but also of relevance to other types of network, is the survivability of the network as a whole when a single node or link fails. When there is a failure of a single node or link, it is important that the rest of the network can continue to function without significant loss of traffic. The design of telecommunications networks which are capable of sustaining multiple failures without a catastrophic loss of performance is an important task in telecommunications network design.

5. STO - Steiner tree problem

In a new "green field" telecommunications network design, if there is already an existing network of source or sink (SS) nodes as well as links, then adding new exchange nodes to the existing network at different locations and optimizing the placement and type of these nodes as part of the overall network design is classified as the Steiner tree problem (STP).

6. CLP - concentrator location problem

In local access loop design, this is the problem of designing the network so as to minimize the cost of connecting a single access point to the nodes. It is also known as the multipoint line optimization problem (MPO).

7. FAP - frequency allocation problem

In mobile telecommunications networks comprising a number of fixed base stations and a number of mobile handsets, if adjacent base stations are allocated communications frequencies which interfere with one another then the viability of the network is compromised. The frequency allocation problem (FAP) is to allocate frequencies to base stations in a mobile network, so that interference between base stations is minimized, and so that the number of different frequencies used is minimized.

8. RTO - routing table optimization

A routing table contains an address specific sequence of preferred paths through a network for received traffic. It is possible to operate a given network most efficiently by optimally choosing the routes, whether these be fixed or dynamically allocated. A higher overall level of utilization can be achieved by optimizing the choice of routes. The problem is called the routing table optimization problem (RTO).

9. BA - bandwidth allocation

The problem of allocating bandwidth to a link between exchanges is analogous to dimensioning the links. The greater the bandwidth allocated to a particular link, the higher the capacity available to carry traffic on that link. The optimization of bandwidth allocation is connected with routing table optimization.

10. SCA - spare capacity assignment

Within a resilient network, capable of surviving cases of link or node failure, there will be spare capacity. Assignment of spare capacity within the network so as to limit the cost of that spare capacity and to restrict the hop limit in the restoration route is an optimization problem in network design. Spare capacity assignment (SCA) is a hybrid form of survivability optimization (SO) and routing table optimization (RTO).

The basic problem of all network design optimization is to produce a network design of least cost and best performance. In the context of network design, performance can be given different meanings. The starting point for the network can be a specification for a complete new network (green field
5 network) having predetermined design parameters for traffic specification. Alternatively, the starting point for a network design can be an existing network, to which is to be applied a new traffic specification.

Network Hardware component characteristics

10 Any telecommunications network design must specify available components in order to physically construct the finished telecommunications network. Physical hardware components introduce their own constraints in terms of cost, performance, reliability, capacity, the types of telecommunications services which the components support, and the delay
15 which the hardware introduces. These are examples of some of the characteristics of actual hardware devices.

Details of hardware component performance and cost are input as hardware signals comprising data signal matrices. A hardware component may be described in terms of a data signal matrix at an argument, either
20 internal or external, of a tree structure.

Representation of a network as a tree structure

When applying genetic procedures to telecommunications network design, there is a problem of how to represent a physical network as a tree
25 structure before techniques can be applied to the task of designing a network architecture.

Real telecommunications networks consist of a plurality of nodes at which are sited customer equipment, or exchanges, and physical links connecting the nodes. The physical link may be a cable link, or can be a
30 microwave link or the like. Each piece of node or link equipment will have physical performance characteristics and limitations on speed, data capacity, switching capacity and the like, as well as having operating cost and purchase cost characteristics associated with it.

In a preferred process of the present invention, a tree structure is used to describe a network architecture as follows:

TREE COMPONENTS

5 A tree structure of signals for representing a telecommunications network is made up of connecting signals and node signals, the connecting signals connecting the node signals in an hierarchical structure. the connecting signals comprise:

 one or more link signals which create links between nodes of a
10 network map; and

 one of more graft signals which create links between nodes of a network map.

 A plurality of node signals, describe physical exchanges, physical links or customer sites.

15 The link and graft signals appear at the root or at internal arguments of the tree, and the nodes appear at external arguments (the "leaves") of the tree. A hierarchial tree structure is constructed from a plurality of link, graft and node signals. The link and graft signals act as connecting signals for connecting the node signals into tree signals. Some connecting signals are
20 more important in the hierarchical structure than other connecting signals. At outer levels of the structure, each connecting signal connects a pair of node signals. At inner levels of the structure, each connecting signal connects a sub tree with a node signal or another connecting signal, with each sub tree comprising one or more connecting signals and a plurality of node signals. In
25 the hierarchy, some signals have greater connectivity than others in terms of the number of other signals with which they connect.

 Physical equipment, eg exchange equipment, cable or transmission link equipment may be described in terms of matrices of hardware signals. The link, graft and node signals may operate on these hardware signals by
30 specifying arrangements of hardware, eg in terms of specifying the location of hardware components, geographically, the number and type of transmission links or exchanges or customer sites, and how they are connected to each other.

The link signals are used to describe information about physical cable link equipment, and their connection pattern to node equipment. The graft signal is used to denote the joining of physical links or sub-networks at a node equipment, eg an exchange, and the node signals are used to describe
5 node equipment, such as customer site equipment or exchange equipment. The node signal can also be used to describe an existing physical link.

LINK SIGNALS

Referring to Figure 5 of the accompanying drawings, a link signal 501
10 has left and right arguments 502, 503 respectively. Each argument comprises a separate tree signal, or a sub-tree signal describing a separate physical network.

In general the arguments of the link signal can either be a node signal or another link signal, for example referring to Figure 6, the link signal 601
15 has as its left argument node signal 1, 602 and as its right argument node signal 2, 603. In Figure 7, link signal 701 has as its left argument 702 node signal 3, and as its right argument 703 a sub-tree beginning with another link signal 703. Link signal 703 in turn, has left and right arguments, each of which comprise a separate sub-tree signal.

20

GRAFT SIGNALS

Referring to Figure 8, a graft signal 801 has left and right arguments 802, 803 respectively, each of which comprises a separate sub-tree. Each separate sub-tree describes a sub-network of the overall network described
25 by the tree. A graft signal with two arguments may join together at their nearest points, the two sub-networks comprising its arguments at an exchange, the exchange being represented by a node signal along the left argument of the graft signal.

Referring to Figure 9, a graft signal 901 may have as its arguments as
30 either a link signal or as another graft signal. The graft signal can have link signals as each of its arguments, or graft signals as each of its arguments, or a combination of a graft signals and a link signal as the arguments, as shown in Figure 8 herein.

NODE SIGNALS

The tree includes node signals as the "leaves" of the tree structure.

Node signals may represent any of the following:

5

1. a customer site
2. a new exchange
3. an existing exchange
4. an existing link

10

The existing link could physically be a cable, a radio or microwave link or an optical fibre link. Information concerning the range of actual physical links available to the network designer and the actual exchanges available to the network designer and from which the physical network is to be constructed, are found as data signal matrices in the node signals and in the link signals.

For example, where a tree contains as a leaf an exchange node signal, the exchange node signal may comprise data signals concerning the physical location of the exchange, the capacity of the exchange to multiplex telephone signals, the capacity of the physical exchange to switch telephone signals, the delay rating per traffic volume of the physical exchange, a buffer size of the exchange, an initial cost of the exchange, an annual amortisation cost of the exchange, the running cost\annual maintenance cost of the exchange, the "pay as you use" leasing rate of the exchange and an indication of which services can be used at the exchange. The "pay as you use" leasing rate and the initial cost of the exchange can be represented as a cost per traffic unit, in the case of a leased exchange.

For example, where a tree structure is implemented by a computer in the programming language C, the information relating to the physical exchange may be represented as an array of data signals with several components. The data signals structure may be defined by customized C signals as follows:

.exchange_type = "one"

physical location = .x and .y coordinates

The exchange_type in turn contains the following data signals:

5 **.conc** concentration capacity = the capacity of the exchange to concentrate signals

.switch switching capacity = the capacity of the exchange to switch signals

.delay effect = the delay rating per traffic volume of the exchange

10 **.storage** capacity = the buffer size of the exchange

.init_cost = the initial cost of the exchange

.amort_cost = the annual amortisation cost of the exchange

.maint_cost = running cost = the annual maintenance costs of the exchange

15 **.use_cost** = pay as you use leasing rate of the exchange

.service1 = indicates which services can be used at the exchange ie services 1, 2, 3 etc

Similarly, the link signals contain information concerning the physical cable links used to connect exchanges. In the programming language C, a

20 link signal will identify a link by:

an identification **.link_id**

the end locations of a link are given as exchange_ids.

.exchange1 and **.exchange 2**

the length of a link is calculated automatically from the coordinates of the exchanges which it connects.

25 **distance[exchange1][exchange2]**

a type specifying the capacity and other features of the link is represented.

.link_type

The **link_type** data signals structure contains the following information:

30 **.link_type** = "one"

.link_capacity = the maximum number of Kbytes per second which the physical link can carry

.delay effect = the delay rating per traffic volume per distance of the physical link

.init_cost = the initial cost per distance of the physical link

5 **.amort_cost** = the annual amortisation cost per distance of the physical link

.maint_cost = the running cost or the annual maintenance costs of the physical link

.use_cost = the "pay as you use" rate of the physical link

10 **.service1** is used to indicate which services can be used on the link, for example service1, service2, service3 etc.

The **.service1** signal can be used to incorporate varying costs, the cost varying according to the location of the link, if the cost information is included as a cost matrix.

15 OPERATION OF THE LINK AND GRAFT SIGNALS

A link signal causes a processor to inspect components of a tree signal stored in memory. The signal components of the tree signal may comprise node signals, link signals, and graft signals. The processor acts under control of the link signal as follows:

20 (i) firstly the link signal causes a search of the sub-tree in its first (left hand) argument, to search for a node signal. The sub-tree may be a single node signal, or may be a more extensive sub-tree having a plurality of node signals and one or more connecting signals.

25 (ii) having found a node signal in the left sub-tree of its first (left) argument, the link signal causes a search of the right sub-tree of its second (right) argument, for a different node signal to the one found in the left sub-tree. If the link signal happens to find the same node signal as found in the left sub-tree, the link signal keeps searching the right sub-tree until a different node signal is found.

30 (iii) having found a first node signal in the left sub-tree representing a first piece of physical equipment, and a second, different, node signal in the right sub-tree representing a second piece of equipment, the link signal checks to see whether there is an existing link between the two node signals

found in the respective left and right sub-trees.

By "existing link" it is meant that if there are one or more connecting signals (either a link signal or graft signal) which represents a link between the two nodes on the network map represented by the node signals, the nodes representing physical pieces of equipment, then this is considered a link. If there is an existing link, then the link signal does nothing further.

If the link signal does not find an existing link between the two node signals, the link signal creates a new link between those node signals.

In this preferred process the link signal always searches in the order left to right for node signals. Link signals connecting the external arguments of the tree are considered first, before moving inwardly towards the root. Where an argument of the link signal comprises a sub-tree beginning with another lower link signal, the higher link signal will search the left argument of the lower link signal first.

(iv) if the link signal cannot find two different node signals in the respective left and right sub-trees, the link signal calls the graft signal, which then operates instead of the link signal on the same two arguments of the link signal. In this way, if the link signal cannot find two different node signals in the left and right trees, the link signal converts itself into a graft signal.

Operation of the link signal is summarised in Figure 10 herein. The graft signal operates by causing a processor to inspect all the signals in its arguments stored in memory. The signals may comprise link signals, node signals and graft signals as follows.

At step 1001 the graft signal firstly produces a list of all the external arguments (leaves) in each of the two sub-trees in its left and right arguments. The external arguments will generally be node signals.

At step 1002 the graft signal also creates a complete list of all the internal arguments which it can find in the left and right sub-trees. The internal arguments will generally be link signals or graft signals.

If the graft signal finds any external arguments in the left sub-tree already linked to any external argument in its right sub-tree (if it finds that the two sub-trees are already linked) the graft signal causes no further action.

If the graft signal finds that there are no links between any external argument of the left sub-tree and any external argument of the right sub-tree, the graft signal identifies the two closest external node signals, one in the left sub-tree and one in the right sub-tree, relating to the physically closest
5 customer site, exchanges or links and if the geographical distance (in substantially two-dimensional space in the represented network map between the closest node signals) is less than a predetermined amount, the graft signal joins the two external node signals by a link, at step 1003. In effect, the graft signal treats a physical network as two sub-networks of links
10 and exchanges, each sub-network represented by a sub-tree. The graft signal then joins the two sub-networks of the network map representation (if they are not already joined) at their closest exchanges, by creating a new link between the closest exchanges.

If the closest geographical points of the left and right sub-trees are
15 spaced apart from each other by more than the predetermined limit, then the graft signal creates an intermediate node signal between the two closest points of the left and right sub-trees. The intermediate node signal relates to a physical booster station at a node along a physical transmission link.

Operation of the graft signal is summarized in Figure 11. In deriving a
20 network from a tree structure, the signals are considered in the order of outermost leaves first, and working towards the root of the tree. The link signals in the preferred process are considered left to right in the tree, and working from the leaves towards the root, in a hierarchical order of consideration for each main left or right sub-tree extending from the root.

25

Example 1

Referring to Figure 12 of the accompanying drawings, operation of the link and graft signals will now be described. Figure 12 shows a tree having four link signals, two graft signals at internal arguments and at the root, and
30 seven node signals at external arguments (leaves) of the tree

In the tree there appear four exchanges A1, A2, A3 and NSC represented by exchange node signals. The link signals specify a number, which denotes one of the hardware constraints described above, for example

a link capacity of either 25 or 50 Kbytes per second.

A first link signal 1201, denoted link (50), and representing a link having a capacity of 50 Kbytes per second, operates as follows. The first link signal 1201 searches the tree of its left argument for a node signal, and finds
5 a node signal, representing exchange NSC. The first link signal then searches its right sub-tree comprising its right argument for a node signal, and finds the node signal, representing exchange A1. Since the node signals representing NSC and A1 are different, and there is no existing link between these nodes, the first link signal creates a link of capacity 50 Kbytes per
10 second between exchanges NSC and A1. A display of the network map at this stage is shown in Figure 13, with the creation of the new link NL1.

By creating a new link, it is meant that the link signal assigns a particular hardware signal corresponding to a physical link, to the node signals of the left and right arguments.

15 A second link signal 1202 denoted link (25) has as a left argument a node signal which represents the exchange A3, and as a right argument a node signal representing the exchange A1. The second link signal 1202 searches its left sub-tree (in this case just the exchange A3) to find a node signal, and finds the node signal of exchange A3. The link signal then
20 searches the sub-tree comprising its right argument, in this case just the node signal representing exchange A1, to find a node signal and finds the node signal of exchange A1. Since the node signals representing A3 and A1 are different, the link signal creates a new link between them with capacity 25 Kbytes per second, since there is no existing link between the two exchanges
25 A3 and A1. The portion of the network created by the second link signal 1202 is shown in Figure 14 as the new link NL2.

A third link signal 1203, denoting a link of capacity 25 Kbytes per second firstly searches the sub-tree of its left argument, looking for a node signal and finds the node signal of exchange NSC. The third link signal then
30 searches the right sub-tree of its right argument for another different node signal and finds the node signal of exchange A2. After checking that there is no existing link between exchanges NSC and A2, the third link signal creates a new link NL3 of capacity 25 Kbytes per second between exchange NSC

and exchange A2. The corresponding position of the network representation is shown in Figure 15, showing the new link NL3.

A fourth link signal 1204 has as its left argument a sub-tree comprising a node signal of exchange NSC, and as its right argument a sub-tree comprising the second link 1202 together with its respective left and right arguments comprising the node signal of exchange A3 and exchange A1. The fourth link signal 1204 firstly searches its left sub-tree, comprising its left argument, for a node signal, and finds the node signal of exchange NSC. The fourth link signal then searches its right argument and finds node signals of exchange A3 and exchange A1. Since there is no existing link between the node signals found in the left and right arguments of the fourth link signal, the fourth link signal creates a new link NL4 with a capacity of 25 Kbytes per second between the exchanges NSC and A3. The position is shown in Figure 16 as new link NL4.

Operation of the link and node signals has defined the number and type of exchanges and the physical links between them. These are represented as sub-trees. However, the sub-trees are not connected into an overall tree structure having a single root. This is achieved by the graft signal.

A first graft signal 1205 has as a left argument a left sub-tree comprising the third link signal 1203 and its arguments, and as a right argument a right sub-tree comprising the second and fourth link signals and their arguments as described above.

The first graft signal 1205 produces a list of all the signals of the external and internal arguments of the sub-trees within its left and right arguments, as follows:

<u>Left Sub-Tree</u>	<u>Right Sub-Tree</u>
3rd link - link (25)	4th link - link (25)
NSC	2nd link - link (25)
A2	NSC
	A3

A1

5 The first graft signal then searches for node signals in the left and right arguments. If the first graft signal finds a link between any external node signal in the left argument and any external node signal in the right argument, the graft signal does nothing. In this case, since the external node signal representing exchange NSC in the left argument is linked to the external node signal representing A3 (and A1) in the right argument the graft signal does nothing.

10 A second graft signal 205 makes a list of all the external arguments (leaves) and internal arguments in each of its left and right sub-trees, producing the following list:

	<u>Left sub-tree</u>	<u>Right sub-tree</u>
15	1st link - link (50)	1st graft
	NSC	3rd link - link (25)
	A1	4th link - link (25)
		NSC
20		A2
		NSC
		2nd link - link (25)
		A3
		A1

25 Since the second graft signal can find an existing link between a leaf in its left argument and a leaf in its right argument, the second graft signal does nothing. However, in this case, the presence of the graft signal has allowed the network to be represented as a tree structure.

30 The network map of Figure 16 may be represented in the programming language C as follows:

```

    graft ( link50(NSC,A1),
            graft (
                link25(NSC,A2),
                link25(
5              NSC,
                link25(A3,A1)
                )
            )
    )
10

```

For the representation of the network as a tree structure, an initial population comprising a large number of tree structure signals, each representing a particular network are created. Creation of the tree structures is random, with link, graft or node signals being assigned randomly to internal and external arguments of a tree structure. As well as the random assignment of link, graft and node signals to internal and external arguments and to the root of the tree, the topology of the tree structure is itself created randomly with respect to number of levels from the root, number of external arguments and number of internal arguments in each of the left and right sub-trees of the tree structure. However, to reduce the search-space of the process, the tree structures may be generated to incorporate all the initial assumptions, eg node signals representing existing exchanges and existing links.

The size of the randomly generated population may be pre-set. As each tree is created, it may be tested for viability against the viability criteria. Since the aim of the first population is to create a population of viable tree structures, randomly generated trees which fail the viability criteria are not included in the initial population. Trees are created randomly and tested for viability, until enough viable trees have been created to provide a sufficiently large first generation population. The number of individual trees comprising the first generation population may be predefined, although the effectiveness of the process may be compromised where a restrictively low number of individual trees are specified as comprising the first generation population.

Viability and fitness testing

In order for a tree structure to be selected as forming the basis for the next generation population, each tree structure must fulfil the requirements of:

1. viability; and
2. "fitness"

Viability could be broadly described as an absolute test of whether the tree describes a network map which represents a physical network which will actually work, within preselected limits of viability criteria, whilst fitness can be broadly described as how well a physical network obtained by an individual tree fulfils the goals of performance, reliability, cost or any other goals which may be set as a fitness test for the network.

The initial test of viability filters out trees which lead to practically unworkable networks. In a simple example, the viability criteria for a network may be simply whether all the customer sites are connected up. A tree describing a network in which customer sites are connected up will be viable. A tree structure which describes a network in which one or more customer sites are unconnected would be unviable and would be rejected.

Whereas in a preferred process, viability is an absolute test for rejection of a tree, fitness is a relative test for rejection or acceptance of a tree for forming the basis for the next generation. For example in a set of unviable networks, some networks will have better performance, better reliability, better resilience and lower cost than others. These networks will be "fitter" than their contemporary trees of their generation. However, since all trees in the set are not viable, then all trees are rejected for forming the next generation.

A set of trees which are all viable in that they all represent workable networks could, in practice, turn out all to be "unfit" or have poor fitness, in that they are not optimal. For example where a tree includes a large number of unnecessary or redundant links, or unnecessary\redundant exchanges, in other words an over-engineered, over-connected network, although the network may adequately satisfy the performance requirements, having

adequate capacity, low switching delays etc and although the network may be viable on technical viability criteria, and because of the redundancy of links and exchanges the network may be very reliable and survivable, on application of the cost criteria, the network may turn out to be very expensive
5 due to the redundancy of links and exchanges. A fitter network in terms of cost, whilst achieving similar performance, resilience and reliability criteria may be achievable by further evolution of trees of that population through successive populations.

The criteria for viability and fitness can all be predetermined and
10 preset within limits, allowing large flexibility of the preferred process in addressing a wide range of network designs.

In the above example of the trees representing initially over engineered networks, where the "fitness" test is to reduce set-up costs, and trees are selected for forming the next generation on the basis of lowest set-up cost, then subsequent populations of trees could be expected to have less
15 redundancy of hardware components, since components have associated costs. The fittest networks will include fewer and fewer components, and at some stage the fittest trees of a generation will fail the viability test, due to lack of components and inability to meet the viability criteria of reliability, connectivity, capacity, etc. The optimized solutions will be the fittest trees
20 representing the lowest cost networks which still pass the viability test.

The viability and fitness tests may be selected from the same set of parameters. Whether a parameter is used as a viability test or as a fitness test is different from case to case, but may be determined by whether the
25 parameter is used as an absolute ground for rejection of a tree, or a relative ground for rejection of a tree, judged relative to the same parameter of other contemporary trees.

Test parameters for viability include one or more of the following:

- the network must contain all of the external exchanges included
30 in the initial network assumptions;
- exchanges must have the necessary switching and concentration capacity to cope with the traffic on the attached links;

- the network must meet predefined minimum standards in respect of one or more viability constraints as follows:
 - average cumulative delay time along all possible routes
 - maximum number of hops per route
 - 5 - average value of the link capacity ratio
 - acceptable overall cost of the network
 - the meeting of predefined survivability or reliability criteria
- Test parameters which may form the basis of a fitness test include:
- . performance
 - 10 . reliability
 - . resilience
 - . cost

Performance may be described by parameters of delay, percentage
15 utilisation of the network, average number of hops, or percentage blocking.

Reliability may be characterized in terms of parameters of resilience/survivability, percentage blocking, and availability.

The cost parameters may be characterized by parameters of set-up cost, cost to run and use the network, or cost to run and own the network.

20 Fitness testing is performed by creating network signals representing the network from the tree signals, and testing that network data signals in relation to the selected test parameter(s). This is, in effect, a simulation of network performance by modelling the network through its data signals, and testing that data signals by integration with other signals representing the test
25 parameters.

One aspect of performance is the average delay experienced in transferring information. Another aspect of performance is the probability of failure in transferring information, known the blocking or percentage of lost calls. Additionally, reliability can appear as a separate constraint in the
30 network design optimization problem, either as a fixed constraint, or as part or all of the goal of the optimization. In the latter case, the network design optimization problem becomes a survivability optimization when applied to a backbone network. Reliability can be defined as the percentage of lost calls,

or it can be seen as a different measure, more appropriately called survivability.

Survivability is a measure of the network's ability to survive the failure of individual links or nodes without losing its ability to transfer information. For
5 a network to be survivable, there must be at least two separate routes between every pair of data signals sources\receivers which share neither nodes nor links with one another.

A basic problem of all network design optimization is to allocate equipment at nodes of the network and links between the nodes, having
10 optimal characteristics and specification to produce an optimal network. The criteria for being an "optimal" network ie the fitness criteria, may vary from network to network. For example, where high reliability is required, and cost is of secondary importance, an optimal network will be a highly reliable network. On the other hand, where reliability is not as important as cost, then
15 an optimal network will be a less expensive network, albeit with reduced reliability.

It is possible to set minimum or maximum acceptable values for any of the fitness test parameters so that the optimization process will limit its search to designs which fall within these limits. These may be entered as
20 fitness limit signals. Calculating the actual values for the goals for a particular network design usually requires data signals concerning source traffic, and data signals concerning the performance of a simulation exercise, in order to estimate the traffic at different parts of the network.

The test parameters of performance, reliability and cost may be
25 described as network dependent attributes, because they are dependent upon the physical constraints of the network and its components. In addition to dependent network attributes, there are also other definable attributes of the network which at the outset are independent of the network, either because the network is an existing network, and the attributes can be added
30 to the existing network, or because the network is a green field design.

Independent network attributes include the location of nodes, the location of links, the node capacities, the link capacities, the node abilities, the link abilities and the services available.

- Node locations may be specified as being able to be placed anywhere, or at restricted sites, or at fixed sites, or at some fixed sites, or at any SS node, or at only some SS nodes. This is implemented by inputting the locations as network constraint signals or network assumption signals. Link
- 5 locations may be specified as being placable at any node, only at some nodes, being fixed, having some link locations fixed, being placed at any SS nodes, or being placed at only some SS nodes. Node capacities can be specified as of any capacity, of a discreet value, or being a fixed capacity, or only some being a fixed capacity.
- 10 Link capacities can be defined as being capable of adopting any capacity, of only discrete capacities, or of being a fixed capacity, or only some being a fixed capacity. Node abilities can be preset prior to optimization as allowing the node equipment to supply all services, only some of the services available, switching, and all concentration. The link abilities can be
- 15 predetermined as being capable of supporting all services, only some services, switching, and all concentration. The services available may be single services or multiple services. Routing tables may be fixed, fixed by a rule, adopt any routing table, adopt any routing table with certain rules, or having only some routing fixed.
- 20 At the start of the network design, the basic problem can be stated as finding the best way to connect together a series of locations using existing or new exchange equipment and links, so as to achieve a required transport capacity between those locations within certain performance constraints, and at minimum cost. The above described variety of dependent network
- 25 attributes and independent variable network attributes give rise to a vast number of possible variations. It is always be necessary to make some initial assumptions about the type of network required, in order to simplify the design possibilities.
- 30 In the preferred method herein, initial assumptions about the problem are defined initially. In the case of the preferred process described herein, initial assumptions about the network may be given in the form of input signals representing the number of nodes required, the physical location of the nodes, and the traffic volume through those nodes.

In the preferred process, implemented in the programming language C, the number of locations required may be specified by the function:

Identity = 0

external_exchanges[n].exchange_id

5 The physical location of the nodes may be described by the function:

Physical location = x and y co-ordinates (or else a single number indicating a location in a raster scan of a specific area).

external_exchanges[n].x and y

10 The traffic volume may be specified in one of three forms:

Firstly as a traffic matrix, which equals the number of Kbytes per second required between each pair of external exchanges. In the case of the C implemented process, the function may take the form of:

format of matrix = path_capacity[exchange1]

15 **[exchange2]**

If this format is used then the exchanges(exchange1) .matrix value is set to 0, otherwise it is set at 1.

Secondly, the number of users of each required service at each external exchange, and the total levels of outward traffic of these services at the exchange may be specified by the function:

**exchanges[exchange1].users1 and exchanges[exchange1]
.alevelall**

Thirdly, the total outward traffic level at the exchange may be specified by the C signal:

25 **exchanges[exchange1].mlevelall**

All traffic levels should be specified as two values, a maximum bit rate, and an average bit rate for continuous use over an 8 hour day. For example, as the function:

exchanges[exchange1].mlevel1 and .alevel1

30 The characteristics of the available exchange and link types also need to be specified using the parameters listed above.

Additionally, **performance**, location or cost constraints which apply to the desired network can be specified. In the C language, performance

parameters can be specified by the function:

link_capacity,avemaxdelay,avenohops,storage_capacity.

Cost parameters may be specified in the C language as:

total_cost, fixed_cost, vary_cost.

5

Selection of fittest trees

Viable trees are selected on the basis of their "fitness" as measured by the selected test parameter applied to the network which the tree represents. Selection is in relation to other trees. The absolute number of selected trees, or the percentage of selected trees of the population may be set, or trees may be selected provided they achieve a predetermined fitness criteria.

10

The limits of fitness are input as fitness limit signals.

15 Evolution of tree populations

After testing each individual tree of the population for fitness, and selecting the most successful trees of the population to form the basis of the next generation, the selected trees are evolved to form a new population. Evolution of the selected trees to the new population may take the form of retaining the fittest tree structures forming a proportion of the selected trees, and carrying these forward in unmodified form into the next population. Other selected tree structures, forming another proportion of the selected trees, may undergo change by the mechanisms of crossover, mutation, or permutation.

20

Consider the problem of optimizing a new network connecting customer sites CS1, CS2, CS3 and CS4 to existing exchanges EX1, EX2 and EX3, where existing exchanges EX1, and EX2 are already connected by an existing link EL1. The customer sites, existing exchanges and the existing link can each be represented by node signal N1 to N8. The situation is shown in simplified form in the network map representation of Figure 18.

30

CROSSOVER

Referring to Figure 18 of the accompanying drawings, there is shown a tree of an Nth population. The tree describes a network as illustrated in the network map of Figure 19. A list of the corresponding node signals and link signals are shown below, for a new network constructed around exchanges EX1 EX2 and EX3 having an existing link EL1 between exchanges EX1 and EX2. The network in Figure 18 includes intended customer sites CS1, CS2, CS3 and CS4.

	<u>Node signals</u>	<u>Link signals</u>
	N1 = CS1 Customer site 1	L1 = NL1 New link 1
10	N2 = CS2 Customer site 2	L2 = NL2 New link 2
	N3 = CS3 Customer site 3	L3 = NL3 New link 3
	N4 = CS4 Customer site 4	L4 = NL4 New link 4
	N5 = EX1 Exchange 1	L5 = NL5 New link 5
	N6 = EX2 Exchange 2	L6 = NL6 New link 6
15	N7 = EX3 Exchange 3	
	N8 = NN1 New node 1	
	N9 = EL1 Existing Link 1	

The tree structure and corresponding network includes a new node NN1, to which a new link NL1 has been connected. The new node may have arisen through the random generation process of the initial population, or may have been randomly inserted during a mutation process of a previous generation. The existing link EL1, which forms an external argument to the tree (node signal N9) is interpreted as a reference to either of the two nodes signals of exchanges EX1, EX2, making up the two ends of the existing link. Incorporation of an existing link as an external argument improves the efficiency of the whole evolution process in this example. Node signal N9 in Figure 18 operates differently to the other node signals, since it contains information about the existing link, and is treated as a reference to either of the two nodes making up the two ends of the existing link.

Referring to Figure 20 of the accompanying drawings, there is shown a second tree structure of the Nth generation. The second tree structure corresponds to a network having the same exchanges EX1, EX2, EX3 and

customer sites CS1 - CS4 as the network of Figure 19. The network representation described by Figure 20 is shown schematically in Figure 21 herein.

The node signal and link signals of the tree of Figure 20 and
5 corresponding network of Figure 21 are as follows:

	<u>Node signals</u>	<u>Link signals</u>
	N1 = CS1 Customer site 1	L1 = NL1 New link 1
	N2 = CS2 Customer site 2	L2 = NL2 New link 2
	N3 = CS3 Customer site 3	L3 = NL3 New link 3
10	N4 = CS4 Customer site 4	L4 = NL4 New link 4
	N5 = EX1 Exchange 1	L5 = NL5 New link 5
	N6 = EX2 Exchange 2	L6 = NL6 New link 6
	N7 = EX3 Exchange 3	L7 = NL7 New link 7
	N8 = NN1 New node 1	L8 = NL8 New link 8
15	N9 = EL1 Existing Link 1	L9 = NL9 New link 9
		L10= NL10 New link 10

New node 1 is a randomly generated new node.

Referring to Figure 23 herein there are shown the first and second
trees of the Nth generation, denoted as parent 1 and parent 2. The first and
20 second trees of the Nth generation are crossed over with each other to form
offspring 1 and offspring 2 in the N+1th generation. The first tree of the Nth
generation has its right sub-tree 2301 crossed over with a sub-tree 2302 of
the second tree of the Nth generation. Regeneration of two tree structures by
crossover is illustrated in the following example.

25 The sub-tree 2301 of the first parent tree is detached at the internal
argument link 5, and the sub-tree 2302 of the second parent tree is detached
at the internal argument link 5. The second sub-tree 2302 is substituted at
the internal argument of the first tree of the Nth generation in order to
produce the resultant first offspring tree, offspring 1.

30 Similarly, the first sub-tree 2301 is attached to the internal argument
previously occupied by the second sub-tree 2302 in the second parent, in
order to produce the second offspring tree, offspring 2 as shown in Figure 23.

Referring to Figure 24 of the accompanying drawings, there is shown the corresponding network designs constructed in accordance with the parent and offspring trees of the Nth and N+1th generations of Figure 23. The network designs of Figure 24 show only a display of the topology of the networks resulting from the trees. However, further information concerning the exchange capacity, link capacity, cost etc as described above is attached with the link and node signals. This information is also available within the tree representation data, although not displayed in the example topology displays of Figure 24.

10 Referring to Figure 24 the parent network 1 is described by the first parent tree as follows. The link signal link 1 creates a new link NL1 between the node signal CS2 and the node signal NN1. At the next level towards the root of the tree, the link signal link 2 searches its left argument for a node signal and finds node signal CS2 and then searches its right argument for a node signal and finds node signal CS1. The link signal link 2 then creates a new link NL2 between the node signals CS1 and CS2, corresponding to the new link NL2 between customer site 1 and customer site 2.

In the right sub-tree, starting from the outermost external leaves, the link signal link 3 creates a new link NL3 between node signal CS3 representing customer site 3 and node signal EX2 representing exchange 2. At the next level towards the root, at the root of the tree, the link signal link 4 searches its left argument and finds the node signal CS4 corresponding to customer site 4 and then searches its right argument for an external argument and finds node signal CS3 corresponding to customer site 3. Link signal link 4 creates a new link NL4 between node signal CS3 corresponding to customer site 3, and node signal CS4 corresponding to customer site 4.

At the next higher level in the right sub-tree, link signal link 5 searches its left argument and finds external node EL1 corresponding to existing link 1 between exchange signal EX1 corresponding to exchange 1, and exchange signal EX2 corresponding to exchange 2. Link signal link 5 then searches its right sub-tree and finds external argument CS4 corresponding to customer site 4. Since there is no existing link between node signal CS4 and node signal EL1, link signal link 5 creates a new link NL5 between node signal CS4

corresponding to customer site 4, and node signal EL1 corresponding to existing link 1. Since node signal EL1 represents an existing link connected to exchanges EX1 and EX2, link signal link 5 creates the new link NL5 between customer site 4 and exchange 2, being at one end of the existing link 1 nearest the customer site 4. If customer site 4 had been geographically nearer to exchange 1 than to exchange 2, the link signal link 5 would have made the new link NL5 between customer site 4 and exchange 1. However, in this case since the exchange 2 is nearer to the customer site 4, the new link NL5 is created between exchange 2 and customer site 4.

10 The graft signal graft 6 joins the two networks comprising on the one hand CS1, CS2, NN1, NL1 and NL2, and on the other hand EX1, EX2, EL1, CS3, CS4, NL3, NL4 and NL5 at the nearest nodes, CS1 and CS3.

In this example, the viability condition is merely that all customer sites are connected. Thus, although exchange 3 represented by exchange signal EX3, is not connected, and although the node 1 represented by node signal NN1 is a dead end, since these do not affect the viability condition of all customer sites being connected, the network is still viable. However, since new node 1 appears to be unnecessary, it may be that the parent network 1 is not an optimal network since it requires creating the physical link 1 and terminal equipment at the new node 1, and yet this equipment seems to perform no function. The parent network 1 would not be optimal on the grounds of cost, although the redundant link 1 and redundant node 1 would not affect the performance of the rest of the system, and the network may be successful on the performance criteria.

25 The first tree of the Nth generation may be selected for performing the basis of the next generation, since although the network which it represents is not entirely successful in terms of the criteria of performance goals, cost goals, and reliability goals, it is viable and other trees of the Nth generation may give rise to networks which are not much better when measured by these criteria. The first tree of the Nth generation may be selected to form the basis of the next generation if, compared to other trees of the same generation, it is relatively successful. A successful tree could be described as a tree which, when measured against the appropriate predetermined fitness

parameter, performance, reliability or cost, is within the top group or set of trees as measured by that goal. An identical tree in an early generation may be regarded as passing the fitness test, whereas the same identical tree appearing in a later generation may be regarded as an unfit tree. In the early
5 generation, the average level of fitness of the other trees may be low, whereas in the later generation the average fitness of other trees may be high. As generations evolve, the average level of fitness as defined by the test parameters, is expected to increase. In the example of the first tree of the Nth generation, since this leads to a network which has the redundant new
10 link 1 and new node 1, over a prolonged evolution of a large number of generations, this tree would be unlikely to survive, since at some stage it would be expected to fail the cost fitness criteria due to the unnecessary installation of the new link 1 and new node 1.

15 REWRITING OF TREES DURING CROSSOVER

In Figure 23 herein, crossover of the sub-tree 300 with the parent tree produces the N+1th generation offspring tree, offspring 2. The tree offspring 2 has inconsistent link numbers, having a link 3 and a link 4 in the left sub-tree, and another link 3 and another link 4 in the right sub-tree.

20 A sub-process for rewriting the resultant offspring tree, whether produced by crossover, mutation or permutation, is as follows:

REWRITING OF NODE SIGNALS

There are four types of node signals to deal with. The main problems
25 occur when the node signal represents an existing link. The process for rewriting the tree for each type of node signal is as follows. For a customer site node signal (ie this is a source or sink node which may have been prescribed as part of the specification of the original network problem under investigation), no change is required. For an existing node (ie a node which
30 was prescribed after the specification of the original network problem), it is checked that the node identity number is not larger than the highest consecutively numbered node in the network. If it is, then the node identity number is substituted with a randomly chosen node within the network.

For a new node (ie a node which was randomly generated as an additional node for the network), it is checked that the node identity number is not larger than the highest consecutively numbered node in the network. If the node identity number is larger, then its identity number is changed to one more than the highest consecutively numbered node in the network. For example, if a network has M nodes, and the node identity number of the new node M+5, then the node identity number is changed to M+1. Then, a consistency check is run to ensure that any other references to the newly numbered node in the tree have the same node identity number and same characteristics as the node which has had its identity number changed.

For an existing link, represented as a node signal, if the existing link number is one more than the highest consecutively numbered link in the network, and refers to a blank link, then a new randomly generated link is created with the same number. If the link number is greater than the highest consecutively numbered link in the network, then another existing link is randomly chosen from the network instead. Once chosen, the existing link must itself be checked as follows in case an uncorrected link has been selected. If the newly chosen link has a link from a node to itself, then it is altered so that it goes to another legitimate node.

If the newly chosen link refers to any nodes which have identity numbers larger than the highest consecutively numbered node in the network, then another node is randomly chosen within the allowable range of numbered nodes, and is substituted for the node having the identity number larger than the highest consecutively numbered node. If the newly chosen link type is not set, then it is set to a randomly chosen legitimate value.

Example 2

In another example, shown in Figures 25 and 26, a display is produced from network signals relating to a "before and after" network map achieved through the preferred process. Figure 25, is a randomly generated design in the initial population. Figure 26 shows the final optimized design after evolution of a number of generations. The displayed representations of the networks in Figures 25 and 26 in themselves do not contain all the

information to describe the networks. The capacities and type of exchanges and customer sites are represented by the size of the visual representations, and the capacities of the links are described by the size dimension of the links. However other information corresponding to the link and exchange types are contained in the link and node signals supporting the representations of Figures 25 and 26. By printing out the link and node data signals from the computer, there may be produced a complete network design specification, including exchange and link types, capacities, and other physical specifications of the links and exchanges, together with instructions for their connection into the network.

Referring to Figure 27 herein, there is shown a display of an initial network constraint and initial assumptions data signals, in the form of a display showing customer sites, existing exchanges and existing links.

In Figure 28 herein, there is shown a display of a set of first generation network signals corresponding to a first generation tree. There is much redundancy of node equipment and links in the network signals, derived from an optimized tree having undergone evolution over a number of generations.

The optimized network data signals, displayed visually on a display device in Figure 29, includes a reduced number of node equipment and links compared to the first generation network data signals. A telecommunications network is constructed in accordance with the optimized network data signals.

CLAIMS

1. A method of processing data signals representing a plurality of networks, each network comprising a plurality of node equipment at nodes of
5 the network, and connecting the node equipment by a plurality of links each comprising link equipment, said method comprising the steps of:

(a) generating a population of individual hierarchical signals, each describing a respective network;

10 (b) testing each hierarchical signal to check that it represents a viable network;

(c) testing each hierarchical signal which represents a viable network against one or more predetermined test parameters;

(d) selecting a set of said hierarchical signals depending upon a result of said step (c); and

15 (e) evolving said set of selected hierarchical signals to produce a next generation population of hierarchical signals.

2. A method according to claim 1, wherein in said step (a), each said hierarchical signal is generated in accordance with a set of
20 predetermined network constraints.

3. A method according to claims 1, in which in said step (a) each said hierarchical signal is generated by a random or partially random process.
25

4. A method according to claim 1, in which a said hierarchical signal comprises a two-dimensional structure.

5. A method according to claim 4, in which said hierarchical signal
30 comprises a tree structure.

6. A method according to claim 1, in which said step (e) of evolving the plurality of selected hierarchical signals includes randomly

selecting a portion of a first hierarchical signal, and substituting said randomly selected portion with a second randomly selected portion of a second hierarchical signal.

5 7. A method according to claims 1, which includes a process of obtaining a network signal in accordance with an optimized said hierarchical signal, said network signal representing an optimized network.

10 8. A method of arranging data signals describing a network consisting of a plurality of nodes connected by a plurality of links, in which the data signals are arranged in a machine capable of processing data signals, the method comprising the steps of:

 (i) assigning to each node a node signal representing the node;
 (ii) creating a plurality of connecting signals representing said links
15 between the nodes, each said connecting signal having a plurality of arguments; and

 (iii) combining the node signals and the connecting signals into a structure, in which the node signals are connected together by the connecting signals.

20

 9. A method according to claim 8, in which said structure comprises a hierarchical structure.

25 10. A method according to claim 8, in which said node signals and said connecting signals are combined in accordance with a tree structure, said tree structure comprising a root, and a plurality of arguments.

30 11. A method according to claim 10, in which said plurality of arguments comprise one or more internal arguments and a plurality of external arguments.

 12. A method according to claim 11, wherein each node signal is represented as an external argument of the tree, and said connecting signals

are represented as a root or as internal arguments of the tree.

13. A method according to claim 8, in which each said node has a respective said node signal assigned to it.

5

14. A method according claim 8, in which each said link has a respective said connecting signal or a respective said node signal assigned to it.

10 15. A method according to claim 8, in which each connecting signal comprises first and second arguments, and each argument may comprise a said connecting signal or a said node signal.

15 16. A method according to claim 8, in which said connecting signals are each capable of operating to define a link between a first exchange node equipment represented as a first node signal, and a second node equipment represented as a second node signal.

17. A method according claim 8, in which each node signal
20 comprises data describing a corresponding node.

18. A method according to claim 17, in which each node signal comprises data describing a node equipment associated with the node.

25 19. A method according to claim 18, in which a said node signal comprises data describing a link.

20. A method according to claim 8, in which said node signal comprises data describing a position in a substantially two-dimensional space
30 of each of two ends of a link.

1/22

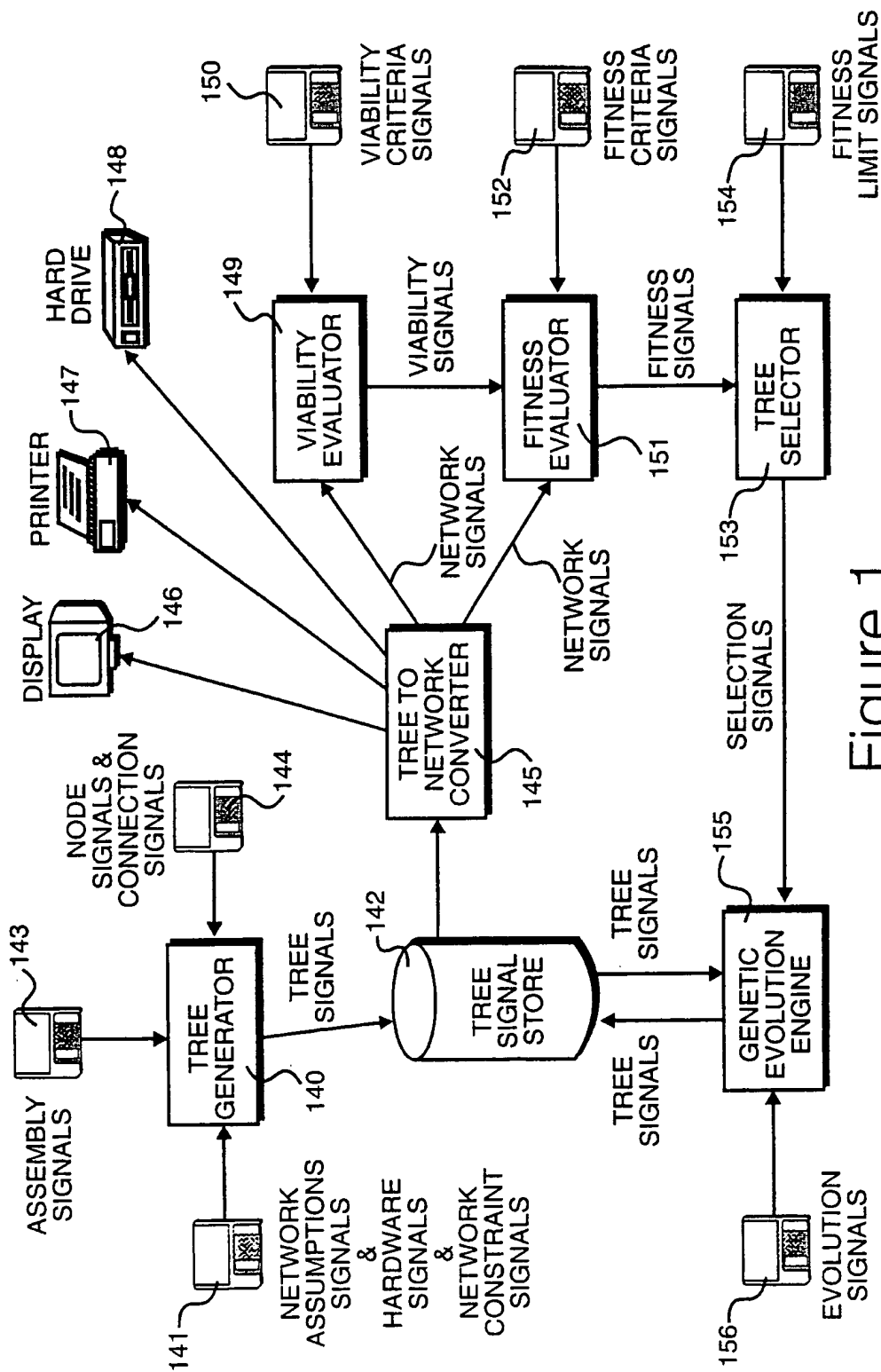


Figure 1

2/22

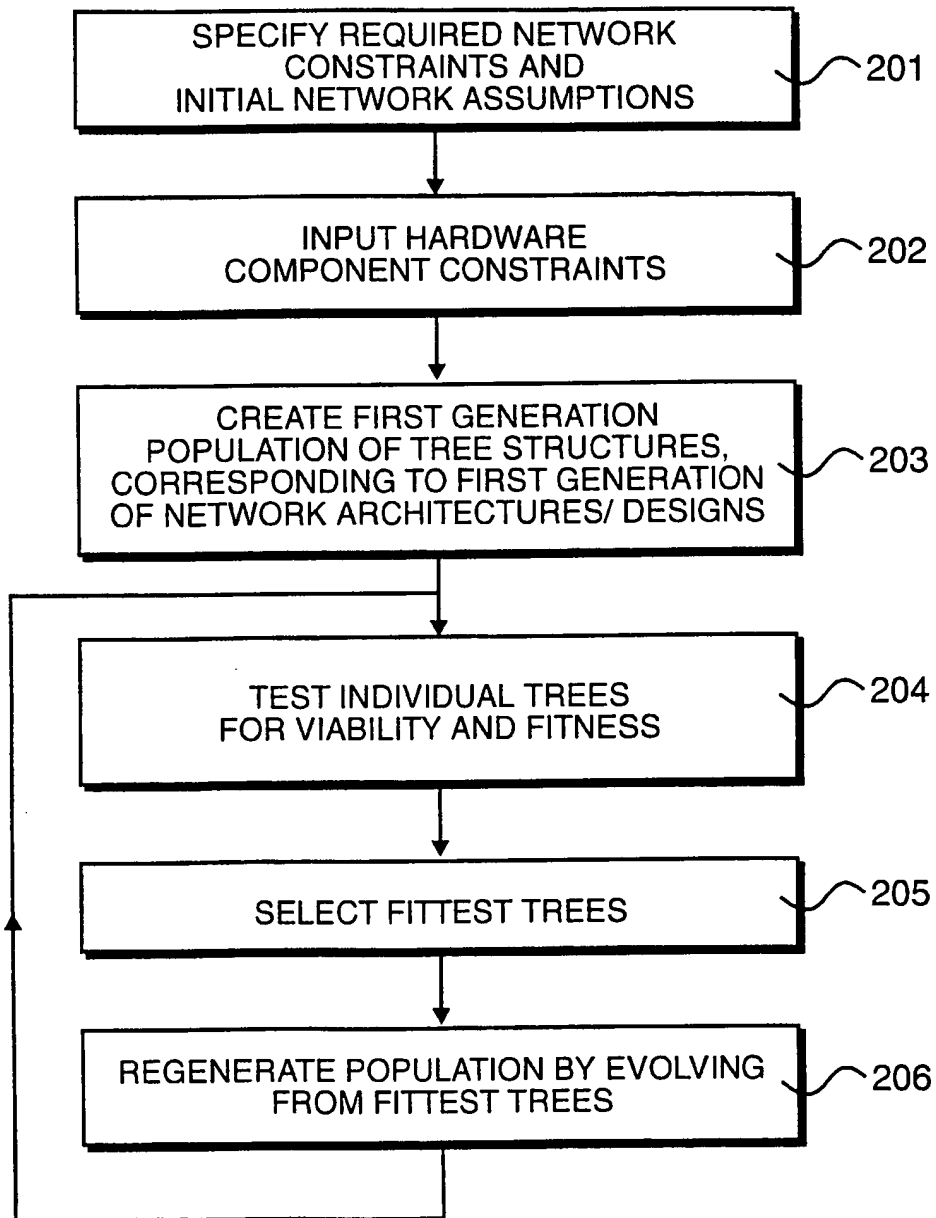
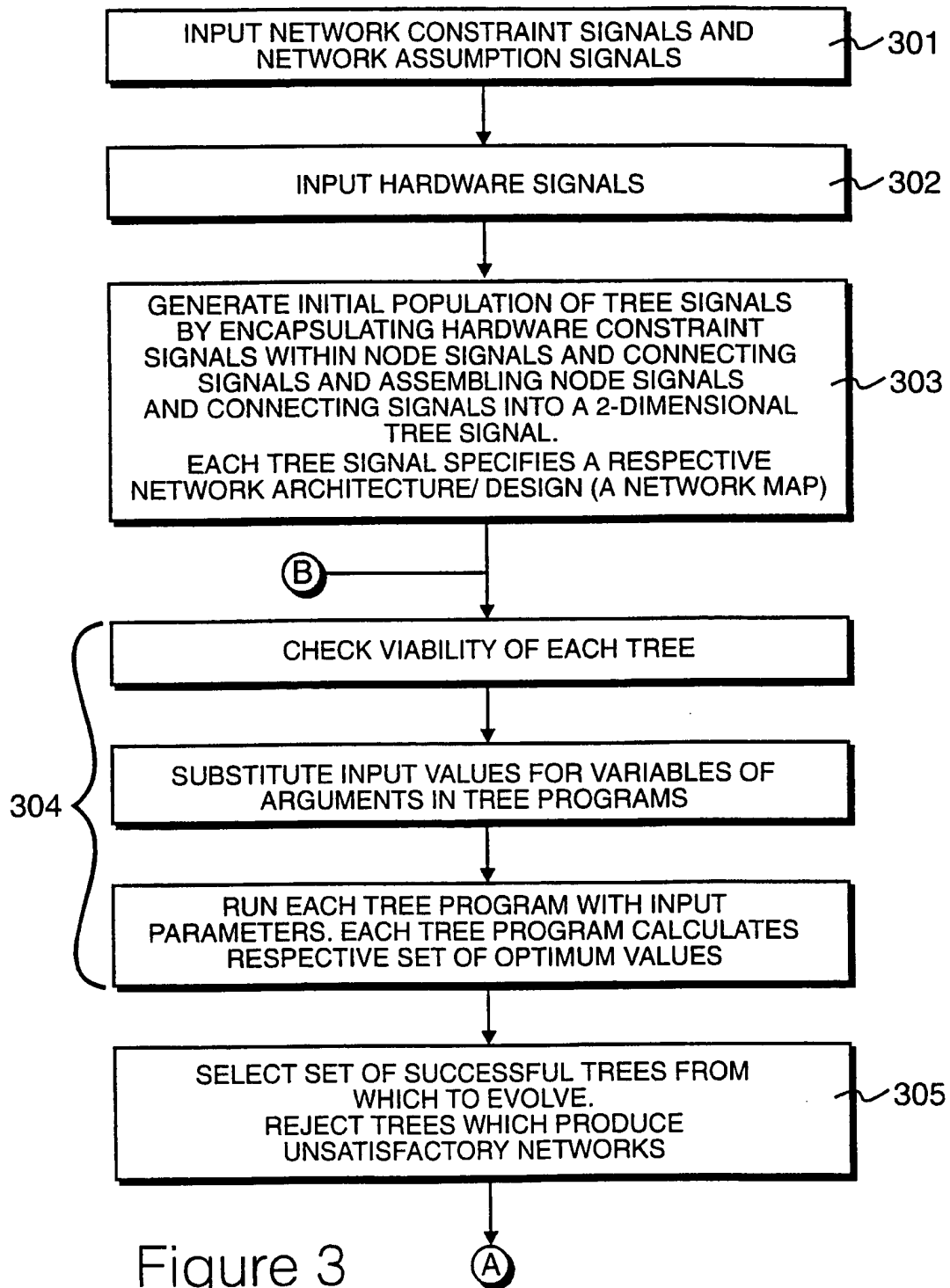


Figure 2

3/22



4/22

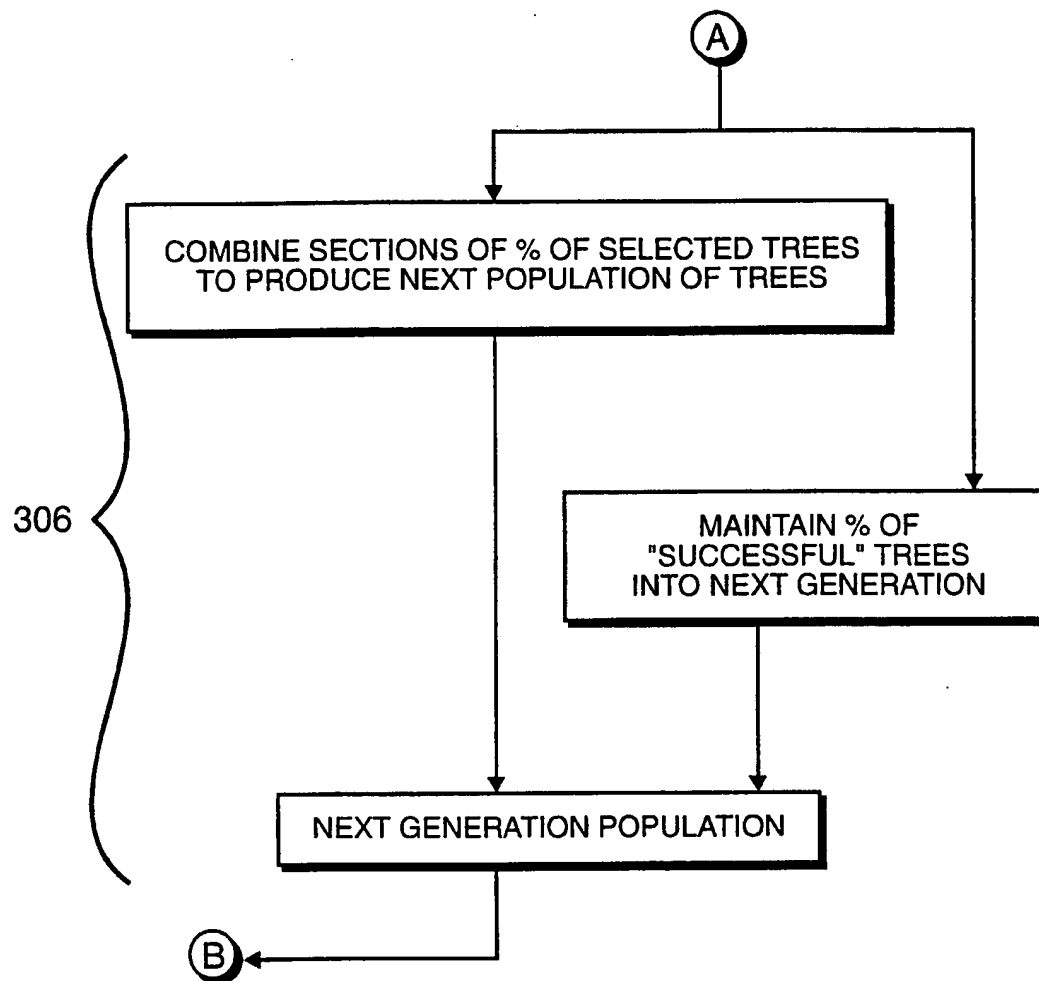


Figure 4

5/22

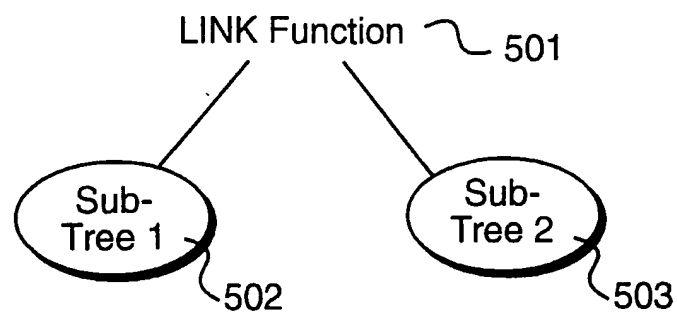


Figure 5

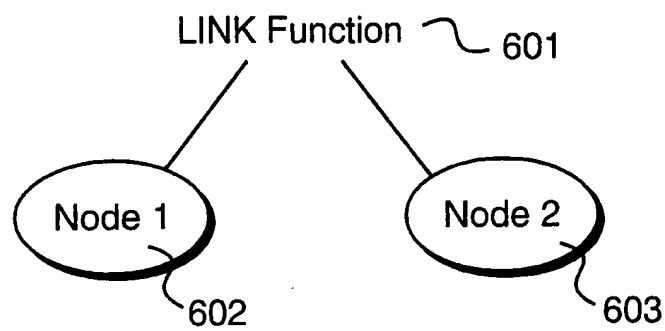


Figure 6

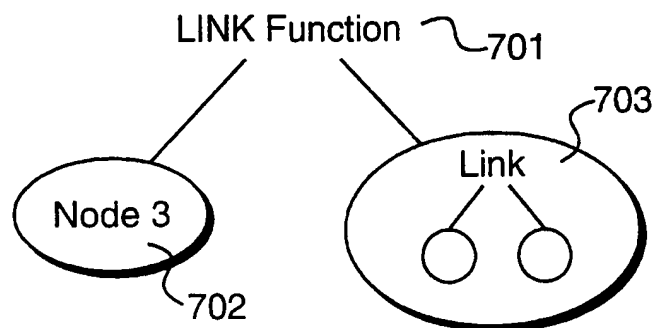


Figure 7

6/22

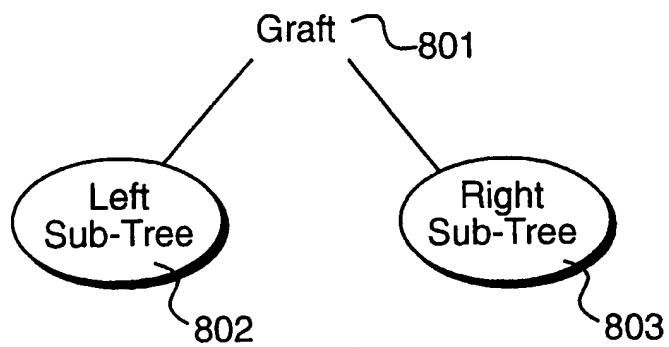


Figure 8

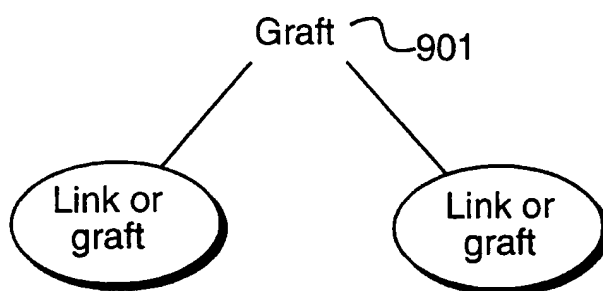


Figure 9

7/22

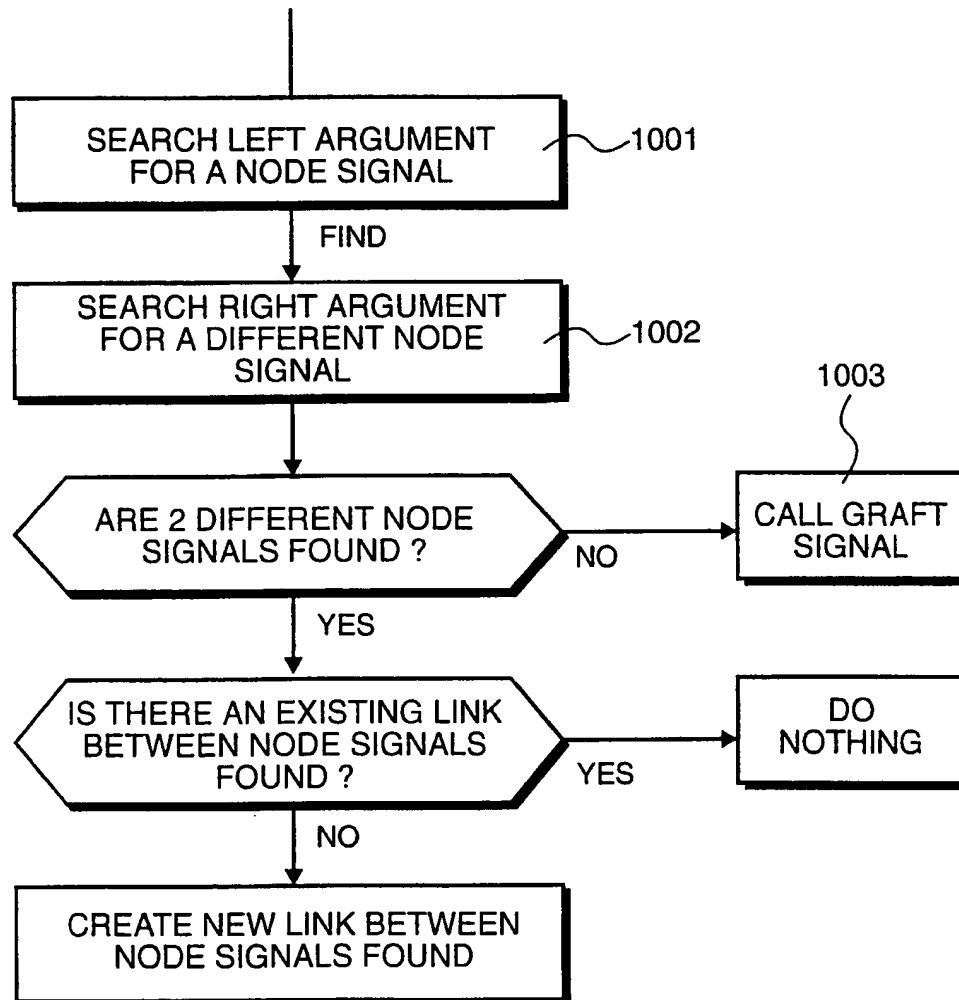


Figure 10

8/22

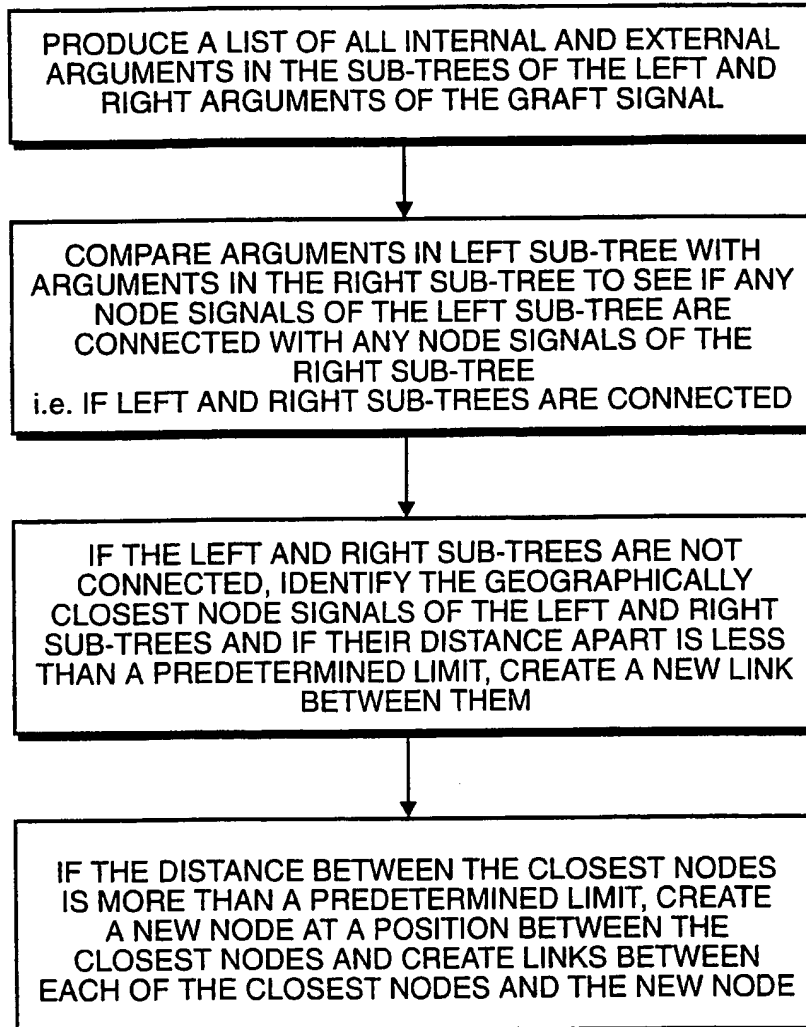
OPERATION OF "GRAFT" SIGNAL

Figure 11

9/22

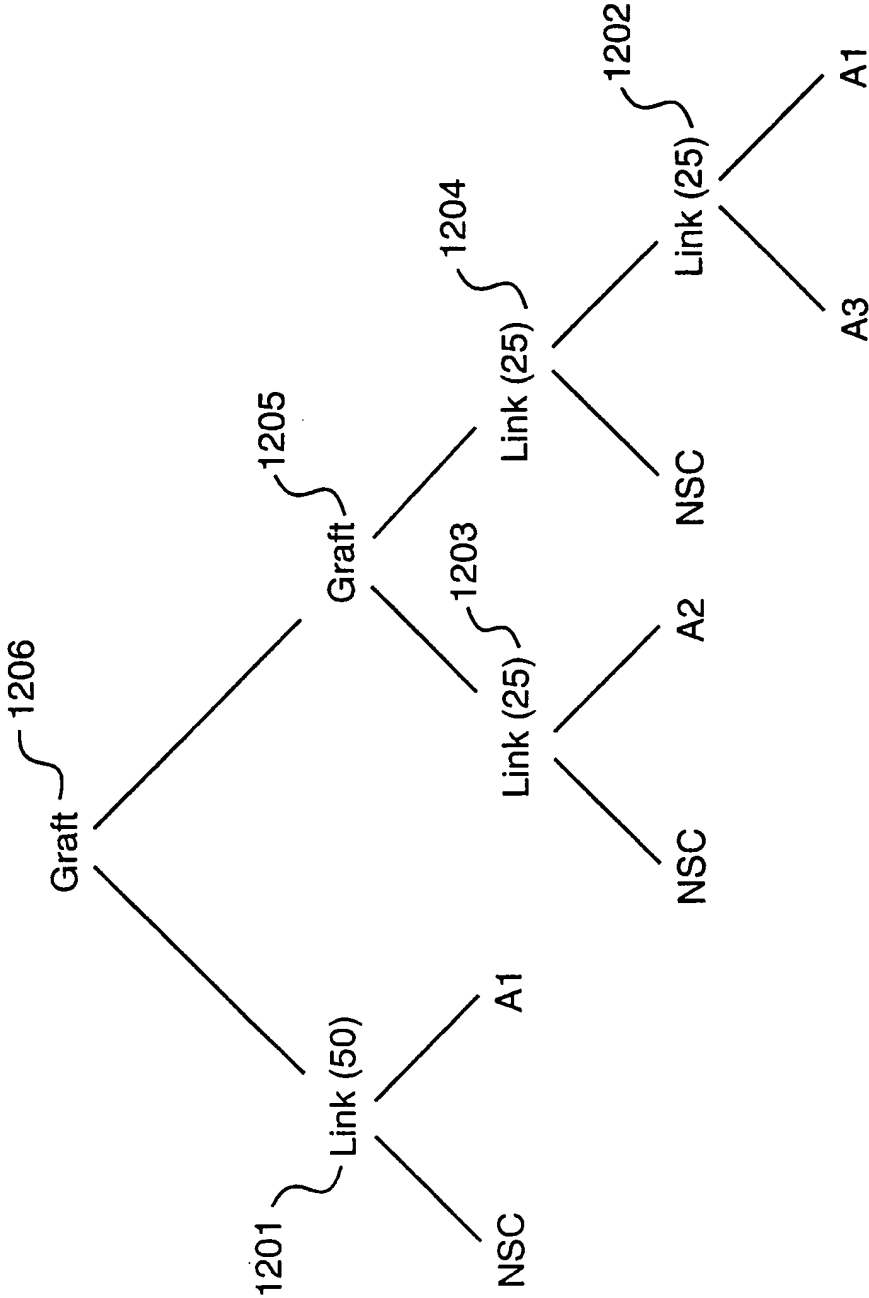


Figure 12

10/22

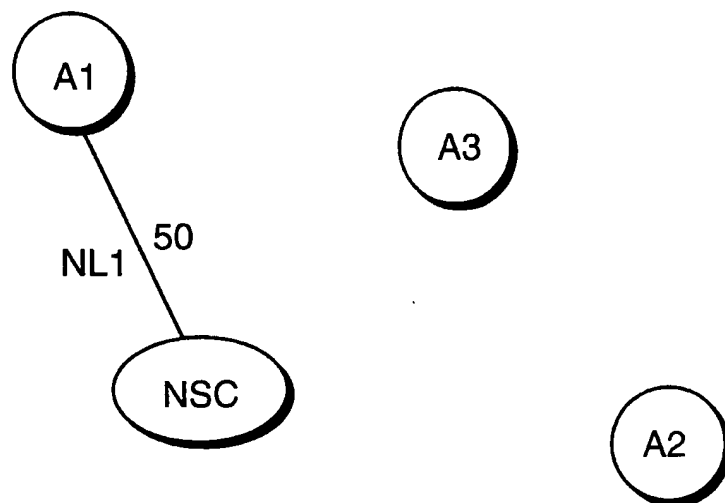


Figure 13

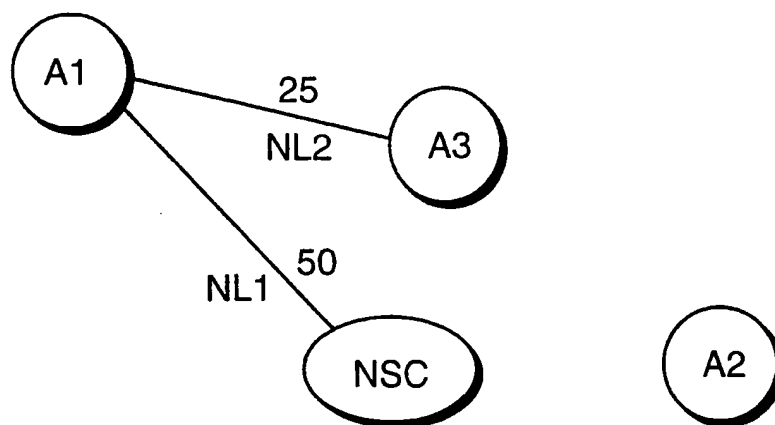


Figure 14

11/22

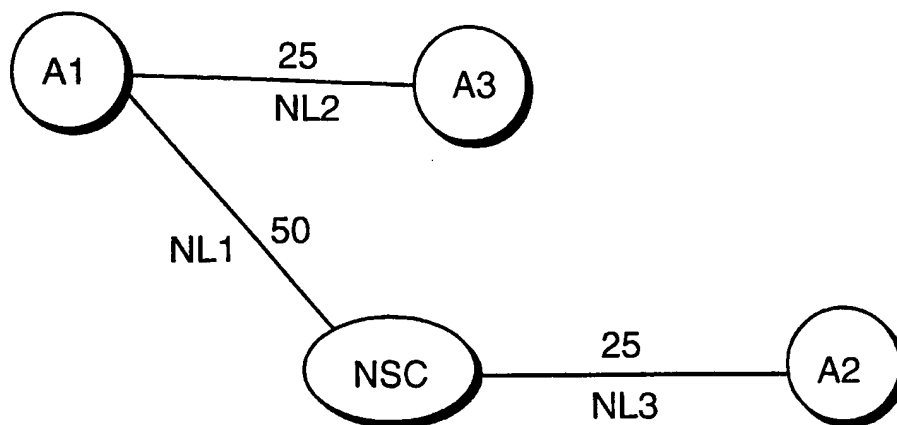


Figure 15

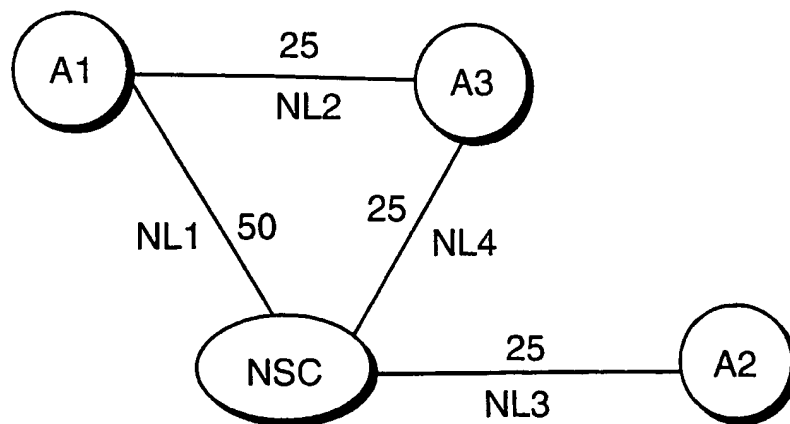


Figure 16

12/22

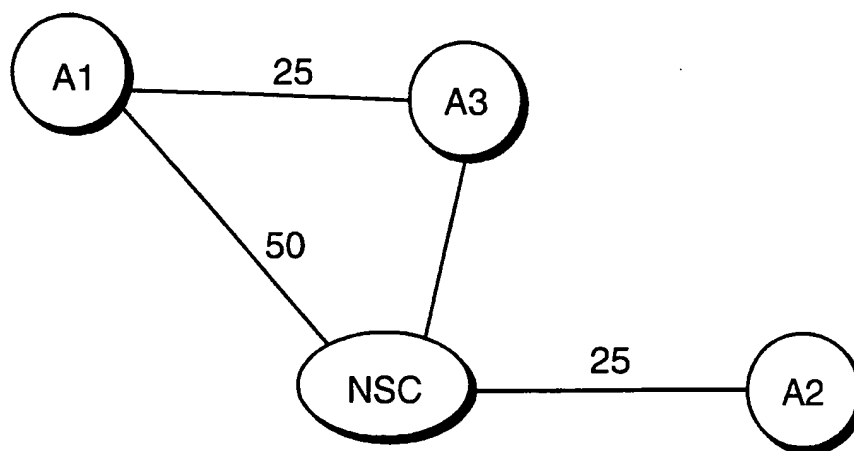
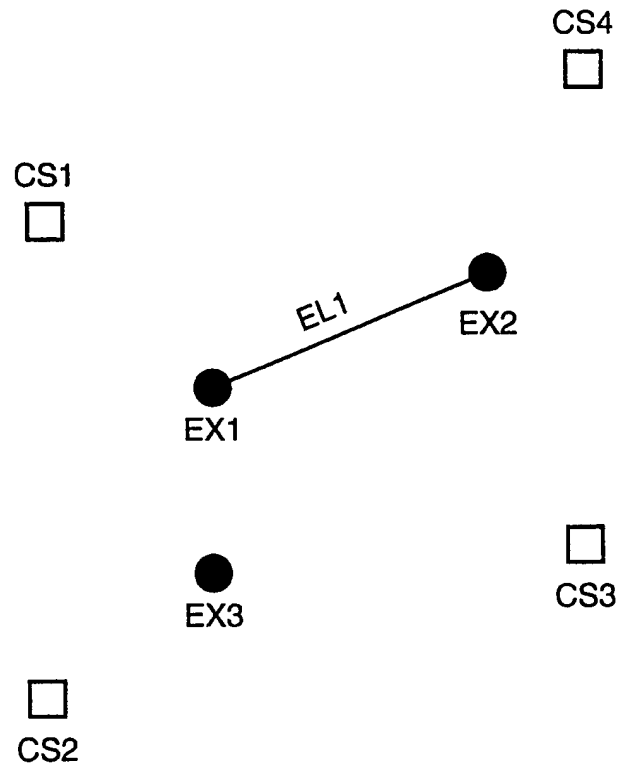


Figure 17

13/22

PROBLEM FOR NEW CUSTOMER SITES



EL1 = EXISTING LINK

EX1 = EXISTING EXCHANGE 1

EX2 = EXISTING EXCHANGE 2

EX3 = EXISTING EXCHANGE 3

CS1 = CUSTOMER SITE 1

CS2 = CUSTOMER SITE 2

CS3 = CUSTOMER SITE 3

CS4 = CUSTOMER SITE 4

ASSIGN NODE FUNCTIONS

N1 → CS1

N2 → CS2

N3 → CS3

N4 → CS4

N5 → EX1

N6 → EX2

N7 → EX3

N8 → EL1

Figure 18

14/22

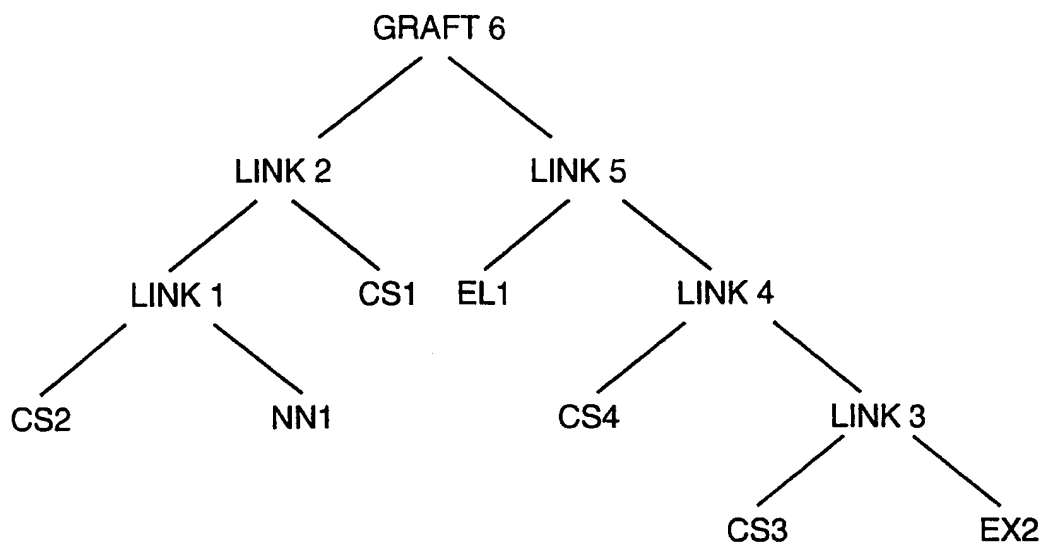


Figure 19

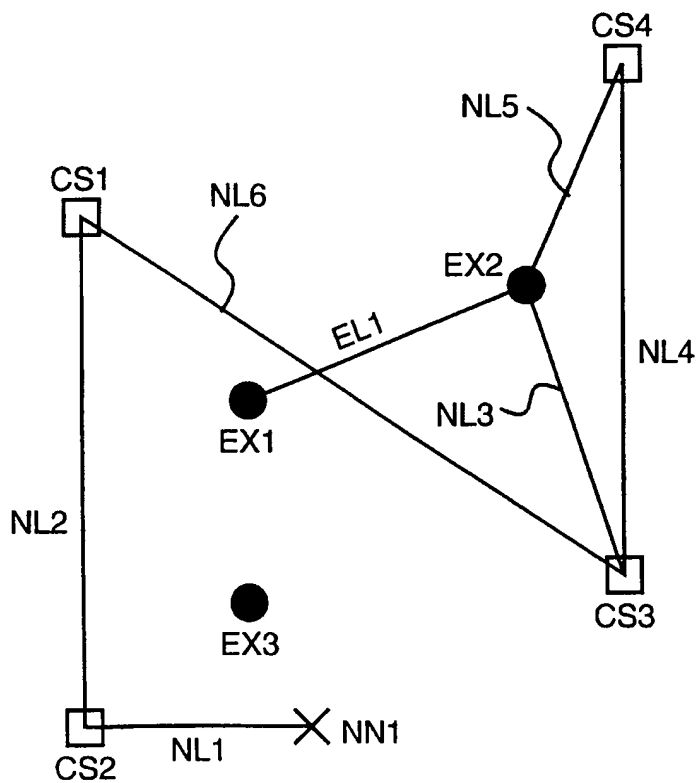


Figure 20

15/22

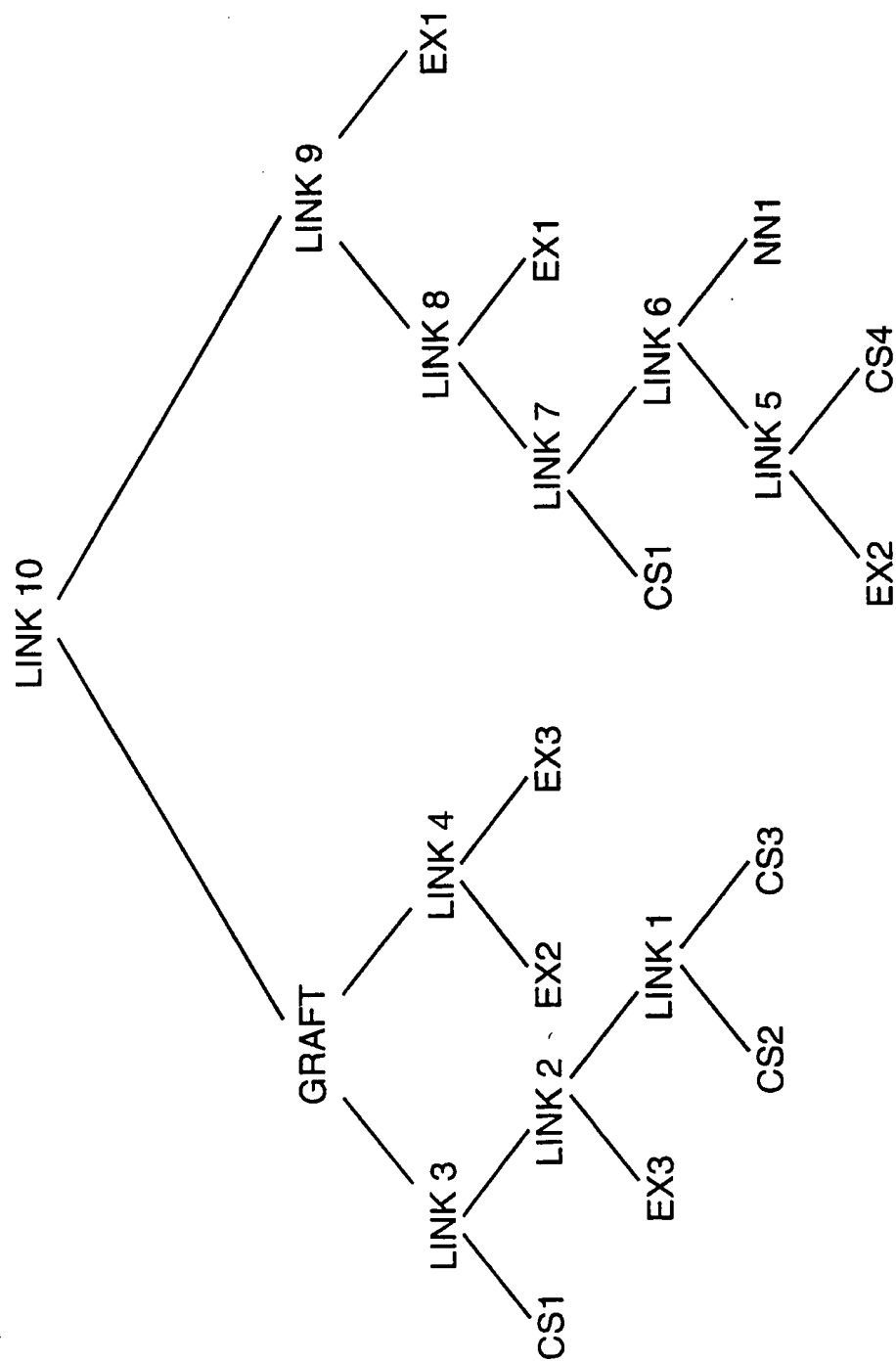


Figure 21

16/22

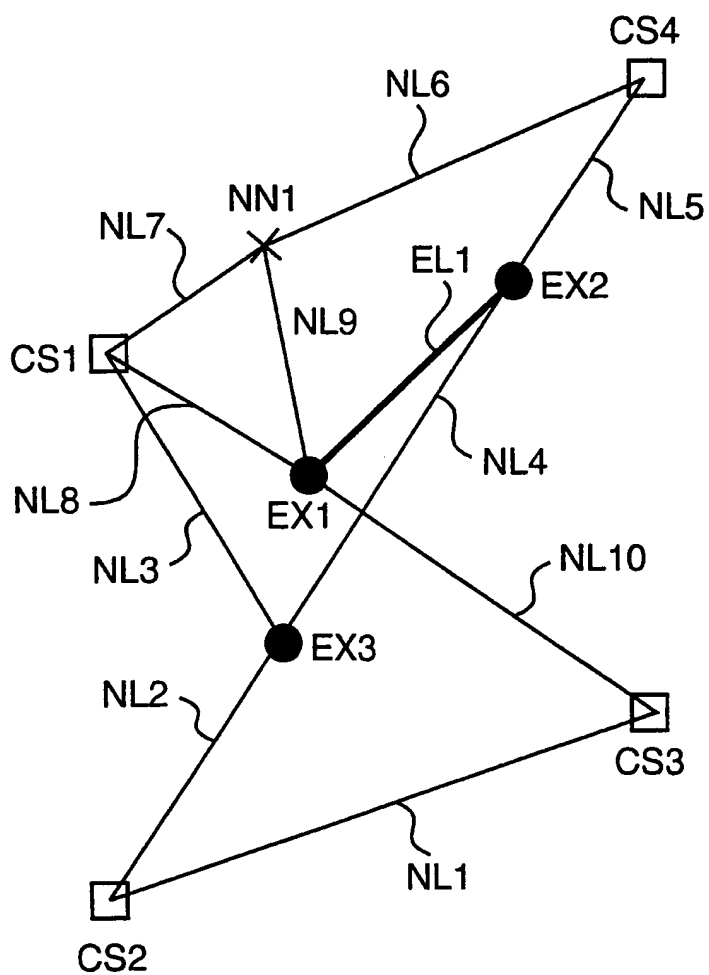


Figure 22

18/22

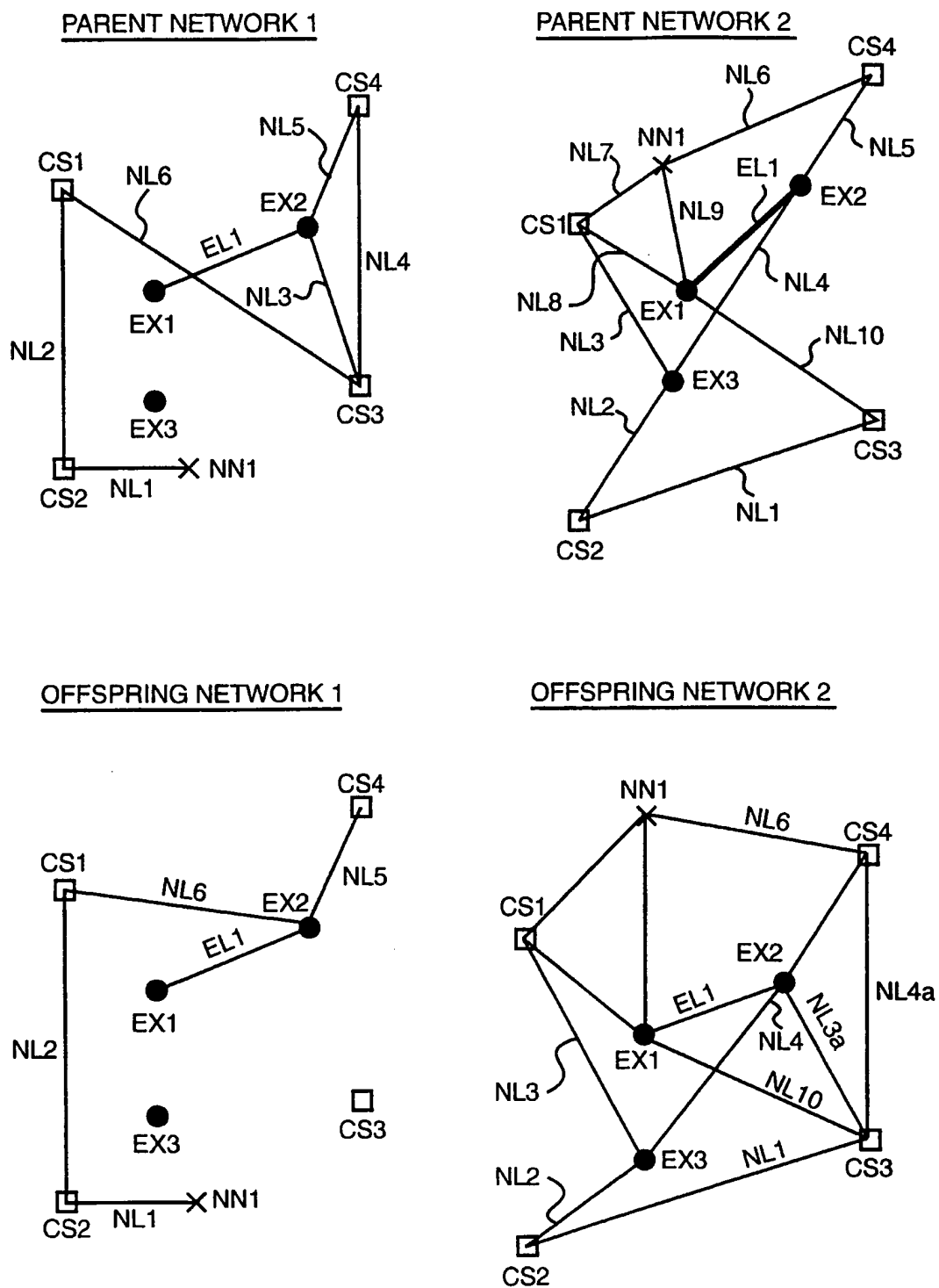
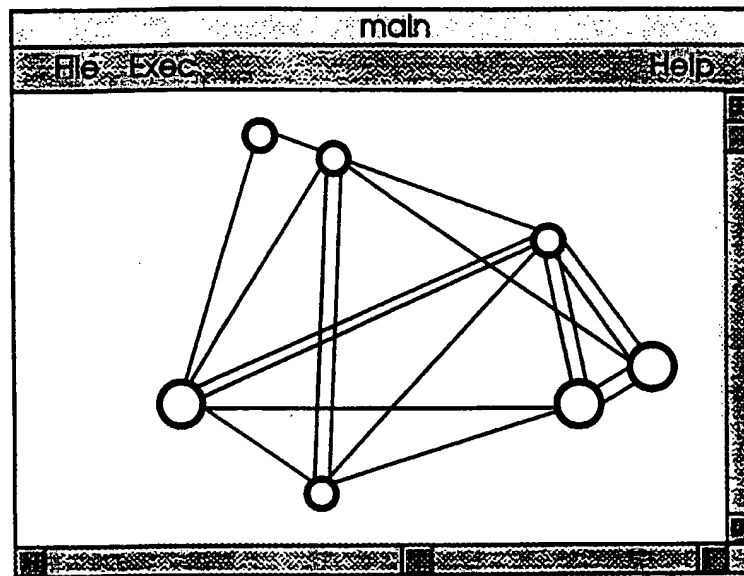


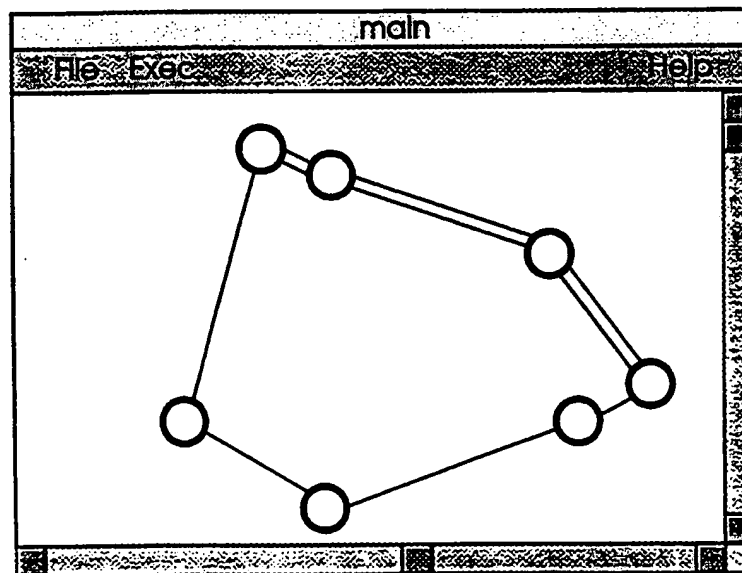
Figure 24

19/22



RANDOMLY GENERATED DESIGN

Figure 25



FINAL OPTIMISED DESIGN

Figure 26

20/22

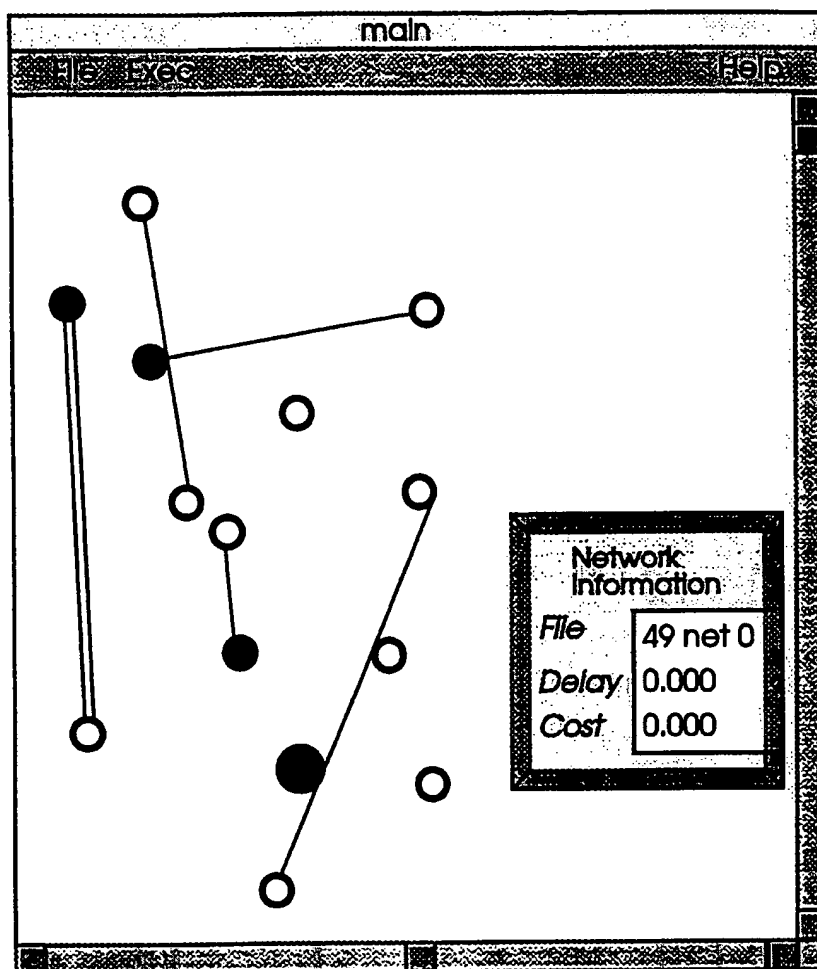


Figure 27

21/22

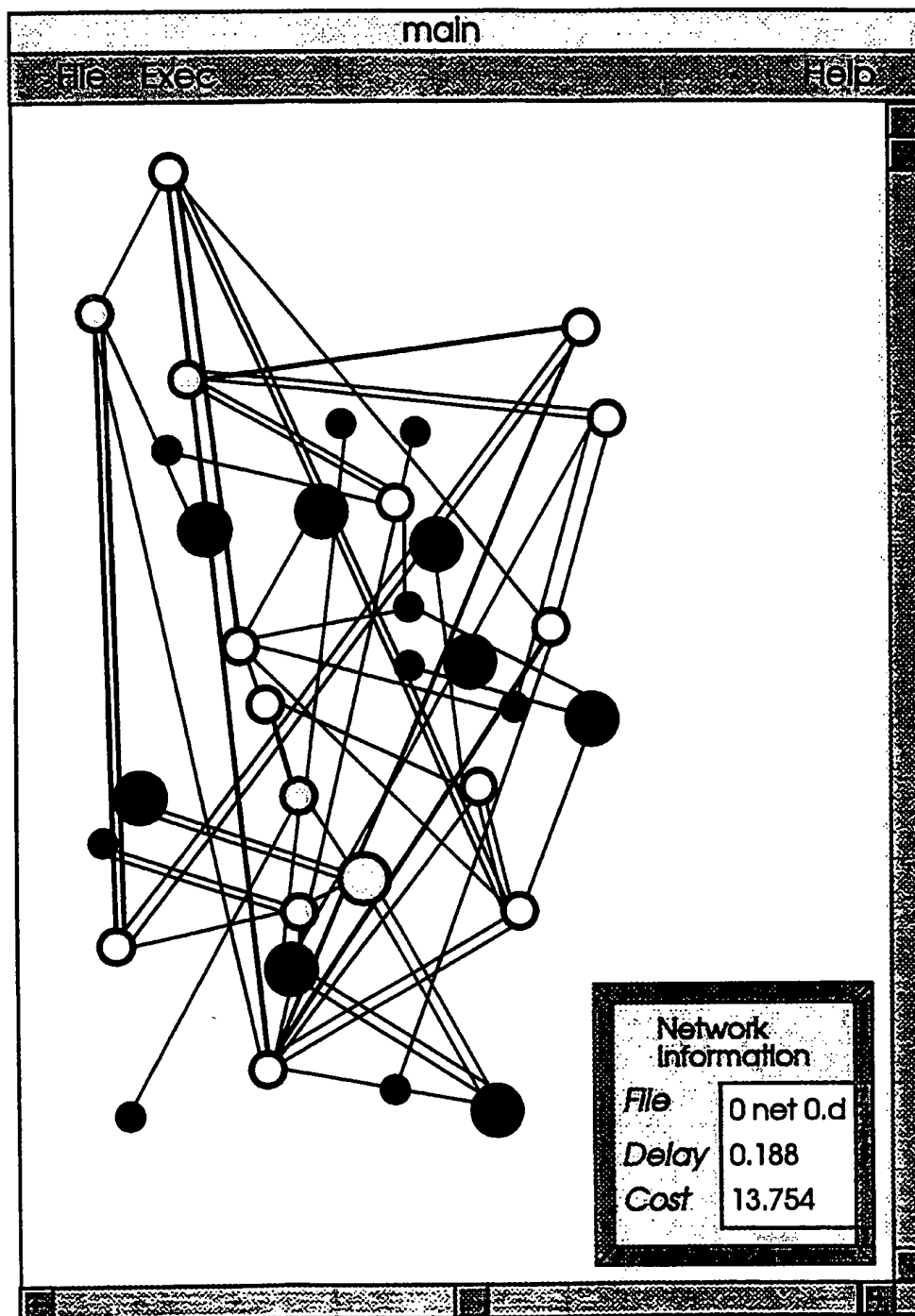


Figure 28

22/22

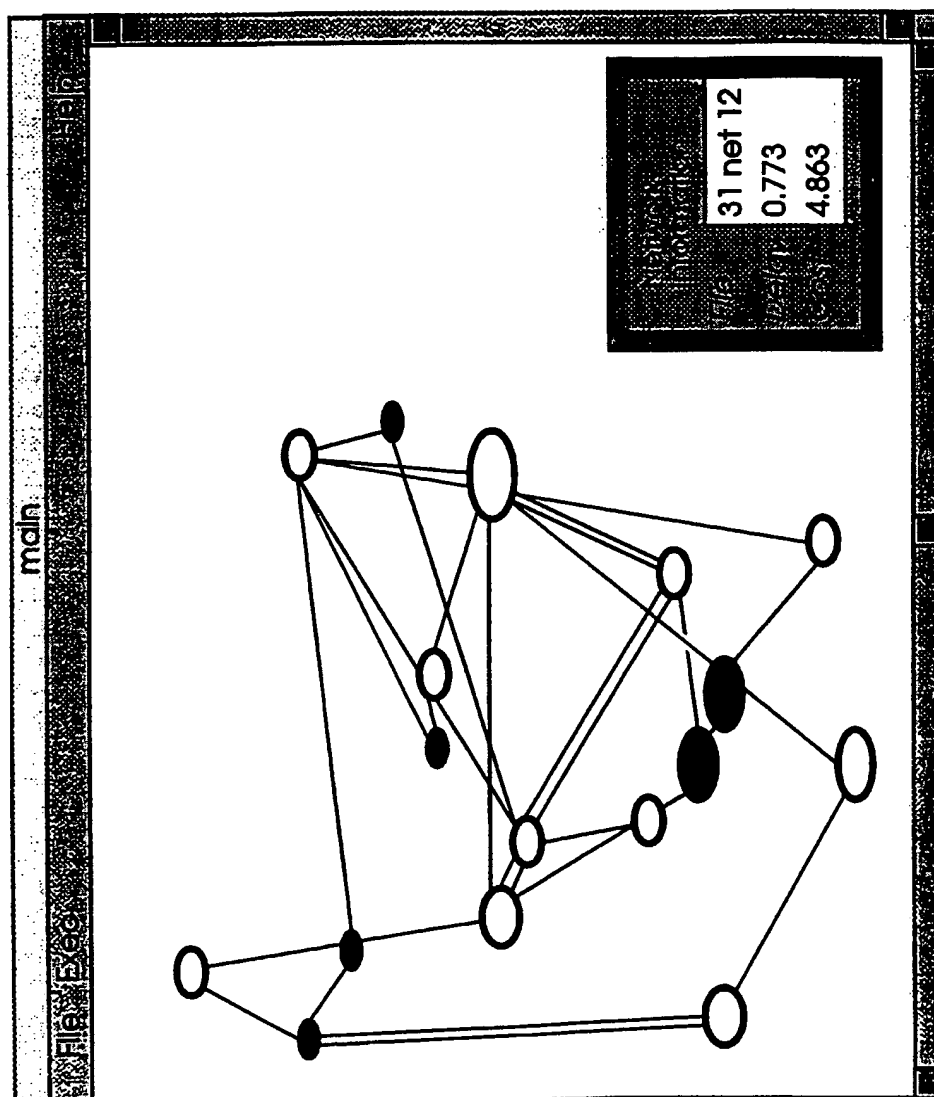


Figure 29

INTERNATIONAL SEARCH REPORT

International Application No

PCT/GB 97/01842

A. CLASSIFICATION OF SUBJECT MATTER
IPC 6 H04Q3/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC 6 H04Q

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	IKEUCHI: "Network constructing Algorithm Based on Link significance Evaluation - NABLE" ELECTRONICS & COMMUNICATIONS IN JAPAN, PART I - COMMUNICATIONS, vol. 73, no. 2, February 1990, NEW YORK US, pages 30-41, XP000140238 see page 34, right-hand column - page 36, right-hand column, paragraph 2 ---	1,2,4
X	US 5 067 148 A (SARDANA) 19 November 1991 see abstract see column 2, line 27 - column 3, line 10 --- -/--	1

☒ Further documents are listed in the continuation of box C.☒ Patent family members are listed in annex.

* Special categories of cited documents :

- *A* document defining the general state of the art which is not considered to be of particular relevance
- *E* earlier document but published on or after the international filing date
- *L* document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- *O* document referring to an oral disclosure, use, exhibition or other means
- *P* document published prior to the international filing date but later than the priority date claimed

T later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

X document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

Y document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.

Z document member of the same patent family

Date of the actual completion of the international search

9 October 1997

Date of mailing of the international search report

06. 11. 97

Name and mailing address of the ISA

European Patent Office, P.B. 5818 Patentlaan 2
NL - 2280 HV Rijswijk
Tel. (+31-70) 340-2040, Tx. 31 651 epo nl,
Fax: (+31-70) 340-3016

Authorized officer

Lambley, S

INTERNATIONAL SEARCH REPORT

International Application No

PCT/GB 97/01842

C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	GRUSZECKI ET AL.: "Some new concepts in demand and traffic forecasting and planning of future telecommunications services" COMPUTER NETWORKS AND ISDN SYSTEMS, vol. 20, no. 1/5, December 1990, AMSTERDAM NL, pages 65-74, XP000172724 see page 68, right-hand column, line 3 - page 69, right-hand column, line 7 ---	1,2
X	OLIVEIRA ET AL.: "A methodology to represent logical network topology information" IEEE NETWORK OPERATIONS AND MANAGEMENT SYMPOSIUM, vol. 1, 14 - 17 February 1994, KISSIMMEE US, pages 196-206, XP000482269 see page 199 - page 200 ---	8,9,13, 16,17
X	STINSON ET AL.: "A state-based approach to real-time telecommunications network management" IEEE NETWORK OPERATIONS AND MANAGEMENT SYMPOSIUM, vol. 2, 6 April 1992, MEMPHIS US, pages 520-532, XP000344720 see page 527 - page 529 ---	8-10,13, 17,18
A	MASE ET AL.: "Traffic design method for large-scale switched telecommunication networks" ELECTRONICS & COMMUNICATIONS IN JAPAN, PART I - COMMUNICATIONS, vol. 78, no. 8, August 1995, NEW YORK US, pages 10-22, XP000547241 see page 11, left-hand column, last paragraph - page 12, right-hand column, paragraph 1 ---	1,2,4
X	PATENT ABSTRACTS OF JAPAN vol. 15, no. 51 (P-1163), 6 February 1991 & JP 02 282829 A (NEC CORP), 20 November 1990, see abstract ---	8,9,13
A	---	17-20
	-/--	

INTERNATIONAL SEARCH REPORT

Internal Application No

PCT/GB 97/01842

C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	DEIRETSBACHER ET AL.: "CNMA: A European initiative for OSI network management" IEEE NETWORK, vol. 9, no. 1, January 1995, NEW YORK US, pages 44-52, XP000486558 see page 45, left-hand column, line 25 - page 47, left-hand column, line 2 see page 49, right-hand column, line 6 - page 50, right-hand column, line 31 ---	8-20
A	MATSUO ET AL.: "Implementation model and execution environment for flexible configuration of telecommunication information systems" IEICE TRANSACTIONS ON COMMUNICATIONS, vol. E77-B, no. 11, November 1994, TOKYO JP, pages 1312-1321, XP000504578 see page 1314, left-hand column, line 12 - page 1315, left-hand column, last line ---	8-13, 17-20
A	ROUVELLOU ET AL.: "Topology identification for traffic and configuration management in dynamic networks" IEEE INFOCOM '92, vol. 3, 4 May 1992, FLORENCE IT, pages 2197-2204, XP000300346 see page 2198, right-hand column, line 6 - page 2200, left-hand column, line 42 see page 2201, left-hand column, line 7 - page 2202, left-hand column, line 37 ---	8-10,13
A	MAYMON: "An information model for configuration management of switching network elements, using OSI tools" INTERNATIONAL CONFERENCE ON COMMUNICATIONS, vol. 1, 23 - 26 June 1991, DENVER US, pages 118-122, XP000269389 ---	
A	CRAVEIRINHA ET AL.: "A survey of applications of mathematical programming to circuit-switched network planning problems" EUROPEAN TRANSACTIONS ON TELECOMMUNICATIONS AND RELATED TECHNOLOGIES, vol. 3, no. 5, September 1992 - October 1992, MILANO IT, pages 499-515, XP000315368 -----	

INTERNATIONAL SEARCH REPORT

International application No.

PCT/GB 97/01842

Box I Observations where certain claims were found unsearchable (Continuation of item 1 of first sheet)

This International Search Report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. ☐ Claims Nos.:
because they relate to subject matter not required to be searched by this Authority, namely:
2. ☐ Claims Nos.:
because they relate to parts of the International Application that do not comply with the prescribed requirements to such an extent that no meaningful International Search can be carried out, specifically:
3. ☐ Claims Nos.:
because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).

Box II Observations where unity of invention is lacking (Continuation of item 2 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

1. Claims 1-7: A method for planning a network by representing it with data signals and using a genetic algorithm to test for viability.
 2. Claims 8-20: A method for defining a network by combining node and link signals into hierarchical/tree structures.
1. ☐ As all required additional search fees were timely paid by the applicant, this International Search Report covers all searchable claims.
 2. ☒ As all searchable claims could be searched without effort justifying an additional fee, this Authority did not invite payment of any additional fee.
 3. ☐ As only some of the required additional search fees were timely paid by the applicant, this International Search Report covers only those claims for which fees were paid, specifically claims Nos.:
 4. ☐ No required additional search fees were timely paid by the applicant. Consequently, this International Search Report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:

Remark on Protest

☐ The additional search fees were accompanied by the applicant's protest.

☐ No protest accompanied the payment of additional search fees.

Information on patent family members

PCT/GB 97/01842

Patent document
cited in search report

Publication date

Patent family member(s)

Publication date

US 5067148 A

19-11-91

NONE

.....